

**DEPARTMENT OF MATHEMATICS**

**MATH2000**  
**Conservative vector fields and line integrals (solutions)**

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(1) Velocity  $\mathbf{v} = \nabla\phi = \frac{\partial\phi}{\partial x}\mathbf{i} + \frac{\partial\phi}{\partial y}\mathbf{j}$ .

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= \frac{y\gamma}{2\pi x^2} \frac{1}{1+(\frac{y}{x})^2} \\ &= \frac{\gamma y}{2\pi(x^2+y^2)} \\ \frac{\partial\phi}{\partial y} &= -\frac{\gamma}{2\pi x} \frac{1}{1+(\frac{y}{x})^2} \\ &= -\frac{\gamma x}{2\pi(x^2+y^2)} \\ \Rightarrow \mathbf{v} &= \frac{\gamma y}{2\pi(x^2+y^2)}\mathbf{i} - \frac{\gamma x}{2\pi(x^2+y^2)}\mathbf{j}.\end{aligned}$$

(2) Method 1:

$$\begin{aligned}\phi(x, y, z) &= \frac{1}{|\mathbf{r} - \mathbf{r}_0|} = \frac{1}{\sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2}} \\ \frac{\partial\phi}{\partial x} &= -\frac{(x-x_0)}{((x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2)^{\frac{3}{2}}} \\ \frac{\partial\phi}{\partial y} &= -\frac{(y-y_0)}{((x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2)^{\frac{3}{2}}} \\ \frac{\partial\phi}{\partial z} &= -\frac{(z-z_0)}{((x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2)^{\frac{3}{2}}} \\ \Rightarrow \mathbf{E} &= \frac{(x-x_0)\mathbf{i} + (y-y_0)\mathbf{j} + (z-z_0)\mathbf{k}}{((x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2)^{\frac{3}{2}}}\end{aligned}$$

Method 2:

Let  $R = |\mathbf{r} - \mathbf{r}_0| = \sqrt{(x-x_0)^2 + (y-y_0)^2 + (z-z_0)^2}$ . Then  $\frac{\partial R}{\partial x} = \frac{x-x_0}{R}$  (see above).

Now

$$\frac{\partial}{\partial x} \frac{1}{R} = \left( \frac{\partial}{\partial R} \frac{1}{R} \right) \frac{\partial R}{\partial x} = -\frac{1}{R^2} \frac{x-x_0}{R} = -\frac{x-x_0}{R^3}$$

so

$$\mathbf{E} = \left( -\frac{x-x_0}{R^3}, -\frac{y-y_0}{R^3}, -\frac{z-z_0}{R^3} \right).$$

(3) Since  $\mathbf{F}(x, y, z)$  is conservative, there is a function  $f(x, y, z)$  such that

$$\begin{aligned}\mathbf{F}(x, y, z) &= \nabla f(x, y, z) \\ &= \frac{\partial f}{\partial x} \mathbf{i} + \frac{\partial f}{\partial y} \mathbf{j} + \frac{\partial f}{\partial z} \mathbf{k} \\ &= 2x\mathbf{i} + z\mathbf{j} + y\mathbf{k}.\end{aligned}\tag{1}$$

Hence  $\frac{\partial f}{\partial x} = 2x$  which implies

$$f(x, y, z) = x^2 + g(y, z).\tag{2}$$

From (2),  $\frac{\partial f}{\partial y} = \frac{\partial g}{\partial y}$ , but from (1),  $\frac{\partial f}{\partial y} = z$ . Hence

$$\begin{aligned}\frac{\partial g}{\partial y} &= z \\ \Rightarrow g(y, z) &= yz + h(z) \\ \Rightarrow f(x, y, z) &= x^2 + yz + h(z).\end{aligned}\tag{3}$$

From (1),  $\frac{\partial f}{\partial z} = y$  and from (3),  $\frac{\partial f}{\partial z} = y + \frac{dh}{dz}$ . Hence  $\frac{dh}{dz} = 0 \Rightarrow h(z) = c$ , where  $c$  is a constant. Thus  $f(x, y, z) = x^2 + yz + c$ .

(4) By definition  $I = \int_C xdx + xydy = \int_a^b x(t)x'(t)dt + x(t)y(t)y'(t)dt$  for  $a \leq t \leq b$ .

(a)  $x'(t) = 2t$  and  $y'(t) = -2t$  so

$$I = \int_0^1 t^2 2t dt + t^2(1-t^2)(-2t) dt.$$

Although we could do this integral directly, it is instructive to set  $u = t^2$  so  $du = 2tdt$  in which case

$$I = \int_{0^2}^{1^2} u du + u(1-u)(-1) du = \int_0^1 u^2 du = \frac{1}{3}.$$

(b)  $x'(t) = \cos t$  and  $y'(t) = -\cos t$  so

$$I = \int_0^{\frac{\pi}{2}} \sin t \cos t dt + \sin t(1-\sin t)(-\cos t) dt.$$

An obvious substitution to make is  $u = \sin t$  so  $du = \cos t dt$  in which case

$$I = \int_{\sin 0}^{\sin \frac{\pi}{2}} u du + u(1-u)(-1) du = \int_0^1 u^2 du = \frac{1}{3}.$$

This provides an example of the fact that the value of line integrals are independent of their parameterization. It also shows how a proof of the general result could be constructed.

$$(5) \text{ (a)} \int_0^1 (x+z)x' + zy' + (y+x)z' dt = \int_0^1 (t+t^3)(1) + t^3(2t) + (t+t^2)(3t^2) dt$$

$$\begin{aligned} & \int_0^1 t + t^3 + 2t^4 + 3t^3 + 3t^4 dt \\ &= \frac{1}{2}t^2 + \frac{1}{4}t^4 + \frac{2}{5}t^5 + \frac{3}{4}t^4 + \frac{3}{5}t^5|_0^1 \\ &= \frac{1}{2} + \frac{1}{4} + \frac{2}{5} + \frac{3}{4} + \frac{3}{5} = \frac{5}{2} \end{aligned}$$

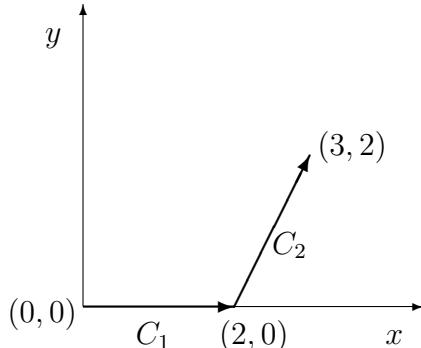
(b)

$$\begin{aligned} \frac{\partial f}{\partial x} = x+z &\Rightarrow f = \frac{1}{2}x^2 + xz + c_1(y, z) \\ \frac{\partial f}{\partial y} = z &\Rightarrow f = yz + c_2(x, z) \\ \frac{\partial f}{\partial z} = x+y &\Rightarrow f = xz + yz + c_3(x, y) \\ \Rightarrow f &= \frac{1}{2}x^2 + yz + xz + c \end{aligned}$$

(c) Since  $\int \mathbf{F} \cdot d\mathbf{r} = \int \nabla f \cdot d\mathbf{r} = f(\mathbf{r}(t_1)) - f(\mathbf{r}(t_0))$ ,  $\mathbf{r}(t_1) = 1\mathbf{i} + 1\mathbf{j} + 1\mathbf{k}$  and  $\mathbf{r}(t_0) = 0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k}$  we have  $\int \mathbf{F} \cdot d\mathbf{r} = \frac{1}{2} + 1 + 1 = \frac{5}{2}$

(d) Since  $\mathbf{r}(t_1) = 1\mathbf{i} + 1\mathbf{j} + 1\mathbf{k}$  and  $\mathbf{r}(t_0) = 0\mathbf{i} + 0\mathbf{j} + 0\mathbf{k}$  we have  $\int \mathbf{F} \cdot d\mathbf{r} = \frac{1}{2} + 1 + 1 = \frac{5}{2}$ .  
Recall that the integral  $\int \mathbf{F} \cdot d\mathbf{r}$  only depends on the end points if  $\mathbf{F} = \nabla f$  for some  $f$ .

(6) Path  $C = C_1 \cup C_2$ .



First we parametrise  $C_1$  and  $C_2$ ; that is, we determine a position vector  $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ .

$$\begin{aligned} C_1 : \quad x(t) &= t, \quad y(t) = 0 : \quad 0 \leq t \leq 2. \\ &\mathbf{r}(t) = t\mathbf{i} \Rightarrow \mathbf{r}'(t) = \mathbf{i}. \\ C_2 : \quad x(t) &= t, \quad y(t) = 2t - 4 : \quad 2 \leq t \leq 3. \\ &\mathbf{r}(t) = t\mathbf{i} + (2t - 4)\mathbf{j} \Rightarrow \mathbf{r}'(t) = \mathbf{i} + 2\mathbf{j}. \end{aligned}$$

We use  $\int_C (F_1 dx + F_2 dy) = \int_C \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = \int_{C_1} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt + \int_{C_2} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt$ .

Here  $\mathbf{F} = xy\mathbf{i} + (x - y)\mathbf{j}$ .

Over  $C_1$ ,  $\mathbf{F}(\mathbf{r}(t)) = 0\mathbf{i} + (t - 0)\mathbf{j} = t\mathbf{j}$  and  $\mathbf{r}'(t) = \mathbf{i}$ . Hence  $\mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) = 0$ . So  $\int_{C_1} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt = 0$ .

Over  $C_2$ ,  $\mathbf{F}(\mathbf{r}(t)) = t(2t - 4)\mathbf{i} + (t - (2t - 4))\mathbf{j} = (2t^2 - 4t)\mathbf{i} + (-t + 4)\mathbf{j}$  and  $\mathbf{r}'(t) = \mathbf{i} + 2\mathbf{j}$ . Hence  $\mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) = 2t^2 - 4t + 2(-t + 4) = 2t^2 - 6t + 8$ .

$$\begin{aligned}\int_{C_2} \mathbf{F}(\mathbf{r}(t)) \cdot \mathbf{r}'(t) dt &= \int_2^3 (2t^2 - 6t + 8) dt = \left[ \frac{2}{3}t^3 - 3t^2 + 8t \right]_2^3 \\ &= \left( \frac{2}{3} \cdot 27 - 3 \cdot 9 + 8 \cdot 3 \right) - \left( \frac{2}{3} \cdot 8 - 3 \cdot 4 + 8 \cdot 2 \right) = \frac{17}{3}.\end{aligned}$$

Thus  $\int_C (F_1 dx + F_2 dy) = 0 + \frac{17}{3} = \frac{17}{3}$ .

Note: in this case, it is unnecessary to parametrise the curve with respect to the parameter  $t$ , because  $x$  is already a suitable parameter. However, we have preferred to illustrate the more general approach.

(7) Setting  $F_1 = 3x^2y^2$  and  $F_2 = 2x^3y$  we see that  $\frac{\partial F_1}{\partial y} = 6x^2y = \frac{\partial F_2}{\partial x}$ .

This implies  $\bar{F} = (F_1, F_2)$  is a conservative vector field. This means there exist a scalar field  $f$  such that

$$\bar{F} = \nabla f = \left( \frac{\partial f}{\partial x}, \frac{\partial f}{\partial y} \right)$$

First  $\frac{\partial f}{\partial x} = 3x^2y^2$  Integrating this we get

$$f(x, y) = x^3y^2 + g(y)$$

Differentiating this and setting equal to  $F_2$  we get

$$\frac{\partial f}{\partial y} = 2x^3y + g'(y) = F_2 = 2x^3y$$

This means that  $g'(y) = 0$ . Integrating we have  $g(y) = \text{constant} = k$  and  $f(x, y) = x^3y^2 + k$ . The fundamental theorem of line integrals is :

$$\int_A^B \nabla f \cdot dr = f(B) - f(A)$$

In our case  $A = (0, 0)$  and  $B = (1, 0)$  and so

$$\int_C 3x^2y^2dx + 2x^3ydy = f(1, 0) - f(0, 0) = 0 - 0 = 0$$