

Lec. 17 MATH2100/2010

17.1

The Convolution Theorem

In general

$$\mathcal{L}(f(t)g(t)) \neq \mathcal{L}(f(t))\mathcal{L}(g(t))$$

and

$$\mathcal{L}^{-1}(F(s)G(s)) \neq \mathcal{L}^{-1}(F(s))\mathcal{L}^{-1}(G(s))$$

However, there is an important relation between f , g , F & G , called the Convolution Theorem:

$$\mathcal{L}^{-1}(F(s)G(s)) = \int_0^t f(\tau)g(t-\tau) d\tau \quad (17.1)$$

(17.2)

Here τ is a dummy variable of integration. If you prefer, call it x or θ or p or... —

The integral on the RHS of (17.1) is called the { convolution } of f and g .
{ folding together }

Sometimes we write

$$\int_0^t f(\tau) g(t-\tau) d\tau = (f * g)(t) \quad (17.2)$$

(or = $f(t) * g(t)$)

* denotes "convolution product"

It is important to note that

$$(f * g)(t) = (g * f)(t) \quad (17.3)$$

(17.3)

$$\text{Pf: } (g * f)(t) = \int_0^t g(\tau) f(t-\tau) d\tau$$

Change variable of integration: Put

$$u = t - \tau \Leftrightarrow \tau = t - u$$

$$d\tau = -du$$

$$\tau = 0 \Leftrightarrow u = t \quad \tau = t \Leftrightarrow u = 0$$

So get:

$$\begin{aligned} (g * f)(t) &= \int_0^0 g(t-u) f(u) (-du) \\ &= \int_0^t f(u) g(t-u) du \\ &= \underline{\underline{(f * g)(t)}} \end{aligned}$$

The Convolution Theorem (17.1) says:

$$\mathcal{L}((f * g)(t)) = \mathcal{L}((g * f)(t)) = F(s)G(s)$$

$$\mathcal{L}^{-1}(F(s)G(s)) = (f * g)(t) = (g * f)(t)$$

(17.4)

(17.4)

Ex 1: $H(s) = \frac{1}{s^3}$

$$= \underbrace{\frac{1}{s}}_{F(s)} \quad \underbrace{\frac{1}{s^2}}_{G(s)}$$

$$\mathcal{L}^{-1}(F(s)) * 1 = f(t)$$

$$\mathcal{L}^{-1}(G(s)) = t = g(t)$$

$$\mathcal{L}^{-1}(H(s)) = \mathcal{L}^{-1}(F(s)G(s)) = (f*g)(t)$$

$$= \int_0^t f(\tau) g(t-\tau) d\tau$$

$$= \int_0^t 1 \cdot (t-\tau) d\tau$$

$$= t \int_0^t 1 d\tau - \int_0^t \tau d\tau$$

$$= t \left[\tau \right]_{\tau=0}^{\tau=t} - \left[\frac{1}{2} \tau^2 \right]_{\tau=0}^{\tau=t}$$

$$= t^2 - \frac{1}{2} t^2$$

$$= \underline{\frac{1}{2} t^2} \quad \text{as we already knew.}$$

17.5

$$\text{Ex2: } H(s) = \frac{2s}{(s^2+1)^2}$$

$$= \underbrace{\frac{2s}{s^2+1}}_{F(s)} \cdot \underbrace{\frac{1}{(s^2+1)}}_{G(s)}$$

$$\mathcal{L}^{-1}(F(s)) = 2 \cos t = f(t)$$

$$\mathcal{L}^{-1}(G(s)) = \sin t = g(t)$$

$$\mathcal{L}^{-1}(H(s)) = \mathcal{L}^{-1}(F(s)G(s)) = (f*g)(t).$$

$$= \int_0^t 2 \cos(\tau) \sin(t-\tau) d\tau$$

$$\left[\text{Use } 2 \sin(A) \cos(B) = \sin(A+B) + \sin(A-B) \right]$$

$$= \int_0^t [\sin(t) + \sin(t-2\tau)] d\tau$$

$$= \sin(t) \left[\tau \right]_{\tau=0}^{t=0} + \frac{1}{2} \left[\cos(t-2\tau) \right]_{\tau=0}^{t=0}$$

$$= t \sin(t) + \frac{1}{2} [\cos(-t) - \cos(t)]$$

$$= t \sin(t)$$

Usefulness in ODEs:

(17.6)

Consider again

$$y''(t) + a y'(t) + b y(t) = r(t)$$

$$y(0) = y'(0) = 0$$

$$\Rightarrow \quad Y(s) = Q(s)R(s) \quad (\text{p. } (16.4))$$

where

$$Y(s) = \mathcal{L}(y(t)), \quad R(s) = \mathcal{L}(r(t))$$

$$Q(s) = \frac{1}{s^2 + a s + b} \quad \begin{matrix} \text{transfer} \\ \text{function} \end{matrix}$$

See now, by Convolution Theorem, that

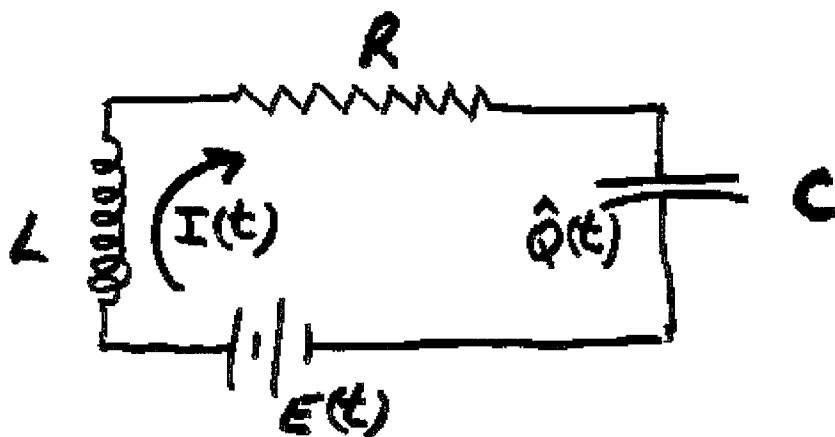
$$\begin{aligned}
 y(t) &= \mathcal{L}^{-1}(Y(s)) = \mathcal{L}^{-1}(Q(s)R(s)) = (q * r)(t) \\
 &= \int_0^t q(\tau) r(t-\tau) d\tau
 \end{aligned} \tag{17.5}$$

where

$$q(t) = \mathcal{L}^{-1}(Q(s))$$

(17.7)

EX 3:



[Here $\hat{Q}(t)$ charge on capacitor - nothing to do with $Q(s)$!!]

As before (p. 1.8, 1.9, 12.1), we have

$$\left. \begin{aligned} L I'(t) + R I(t) + \frac{1}{C} \hat{Q}(t) &= E(t) \\ \hat{Q}'(t) &= I(t) \end{aligned} \right\}$$

$$\Rightarrow L \hat{Q}''(t) + R \hat{Q}'(t) + \frac{1}{C} \hat{Q}(t) = E(t)$$

or

$$\hat{Q}''(t) + \underbrace{\frac{R}{L} \hat{Q}'(t)}_{\text{F}} + \underbrace{\frac{1}{LC} \hat{Q}(t)}_{r(t)} = \underbrace{\pm E(t)}_{f(t)}$$

Suppose also:

$$\hat{Q}(0) = 0, \quad \hat{Q}'(0) = I(0) = 0$$

(17.8)

According to (17.5), the solution is:-

$$\hat{Q}(t) = \int_0^t q(\tau) \frac{E(t-\tau)}{\zeta} d\tau$$

where

$$\begin{aligned} q(t) &= \mathcal{L}^{-1}(Q(s)) \\ &= \mathcal{L}^{-1}\left[\frac{1}{s^2 + \frac{R}{L}s + \frac{1}{LC}}\right] \end{aligned}$$

Form of $q(t)$ will depend on values of R, L, C .

e.g. If $R = 0$,

$$Q(s) = \frac{1}{s^2 + \omega^2}, \quad \omega = \frac{1}{\sqrt{LC}}$$

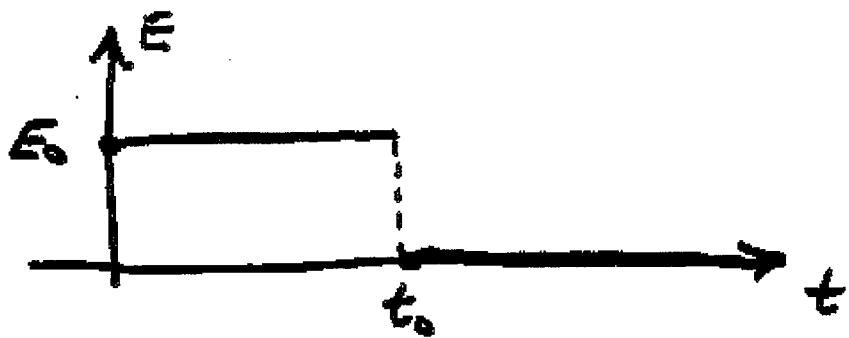
$$\Rightarrow q(t) = \frac{1}{\omega} \sin(\omega t)$$

and

$$\begin{aligned} \hat{Q}(t) &= \frac{1}{\omega_L} \int_0^t \sin(\omega_L \tau) E(t-\tau) d\tau \\ &\quad (\omega_L = \sqrt{\frac{1}{LC}}) \end{aligned}$$

(17.9)

So if



$$E(t) = \begin{cases} E_0, & 0 \leq t < t_0 \\ 0, & t_0 \leq t \end{cases}$$

$$\Rightarrow E(t-\tau) = \begin{cases} E_0, & 0 \leq t-\tau < t_0 \Rightarrow t-t_0 < \tau \leq t \\ 0, & t_0 \leq t-\tau \Rightarrow \tau < t-t_0 \end{cases}$$

we have

$$\hat{Q}(t) = \frac{1}{\omega L} E_0 \int_{t-t_0}^t \sin(\omega \tau) d\tau$$

$$= -\frac{1}{\omega^2 L} E_0 \left[\cos(\omega \tau) \right]_{\tau=t-t_0}^{\tau=t}$$

$$= -E_0 C \left[\cos(\omega t) - \cos[\omega(t-t_0)] \right]$$

$$= 2 E_0 C \sin\left(\frac{\omega t}{2}\right) \cdot \sin\left[\omega\left(t - \frac{t_0}{2}\right)\right]$$

[using $\cos A - \cos B = -2 \sin\left(\frac{A+B}{2}\right) \sin\left(\frac{A-B}{2}\right)$]

(17.10)

Laplace Transform of an integral:

Since $\mathcal{L}(1) = \frac{1}{s}$, $\mathcal{L}(f(t)) = F(s)$

and

$$(f * 1)(t) = \int_0^t f(\tau) \cdot 1 \cdot d\tau$$

it follows from the Convolution Theorem
that

$$\mathcal{L}\left(\int_0^t f(\tau) d\tau\right) = \frac{1}{s} F(s)$$

$$\mathcal{L}^{-1}\left(\frac{1}{s} F(s)\right) = \int_0^t f(\tau) d\tau$$

(17.6)

Ex:

$$G(s) = \frac{1}{s(s^2 - a^2)}, \quad g(t) = ?$$

$$\mathcal{L}^{-1}\left(\frac{1}{s^2 - a^2}\right) = \frac{1}{a} \sinh(at)$$

$$\begin{aligned} \text{So } \mathcal{L}^{-1}\left(\frac{1}{s} \frac{1}{s^2 - a^2}\right) &= \frac{1}{a} \int_0^t \sinh(a\tau) d\tau \\ &= \frac{1}{a} [\cosh(a\tau)]_{\tau=0}^t \end{aligned}$$

(17.11)

$$= \frac{1}{a^2} [\cosh(at) - 1]$$

Ex: $G(s) = \frac{1}{s^2} \frac{1}{s^2 - a^2}$, $g(t) = ?$

Integrating previous answer:-

$$\begin{aligned} \mathcal{L}^{-1}\left(\frac{1}{s^2} \frac{1}{s^2 - a^2}\right) &= \int_0^t \frac{1}{a^2} [\cosh(a\tau) - 1] d\tau \\ &= \frac{1}{a^2} \left[\frac{\sinh(a\tau)}{a} - \tau \right]_{\tau=0}^{\tau=t} \\ &= \frac{1}{a^2} \sinh(at) - \frac{t}{a^2} \end{aligned}$$

Differentiation of Transforms:

$$F(s) = \int_0^\infty e^{-st} f(t) dt$$

$$\begin{aligned} \Rightarrow F'(s) &= \int_0^\infty \frac{d}{dt}(e^{-st}) f(t) dt \\ &= - \int_0^\infty e^{-st} t f(t) dt \end{aligned}$$

$\mathcal{L}(tf(t)) = -F'(s)$, $\mathcal{L}^{-1}(F'(s)) = -tf(t)$ (17.7)

17.12

$$\text{Ex: } \mathcal{L}(\sin(\alpha t)) = \frac{\alpha}{s^2 + \alpha^2}$$

$$\Rightarrow \mathcal{L}(t \sin(\alpha t)) = -\frac{d}{ds} \left(\frac{\alpha}{s^2 + \alpha^2} \right)$$

$$= \frac{2\alpha s}{(s^2 + \alpha^2)^2}$$

Similarly:

$$\mathcal{L}(t \cos(\alpha t)) = -\frac{d}{ds} \left(\frac{s}{s^2 + \alpha^2} \right)$$

$$= \frac{s^2 - \alpha^2}{(s^2 + \alpha^2)^2}$$

Summary:

- 1) Understand Convolution Theorem (no proof) and how to use it to evaluate transforms, and in ODEs.
- 2) Laplace Transform of $\int_0^t f(\tau) d\tau$ equals $\frac{1}{s} F(s)$
- 3) Inverse of the derivative of a Laplace Transform.

$$Kf \cancel{= \frac{s+4}{6-2}, \frac{s+5}{6-5}, \frac{s+6}{6-6}}$$