

Lec. 3 MATH 2100/2010

(3.1)

We were considering

$$y''(t) + 2y'(t) - 15y(t) = 0$$

Let $y_1 = y$, $y_2 = y'$

$$\Rightarrow (*) \quad \tilde{y}'(t) = A \tilde{y}(t), \quad A = \begin{bmatrix} 0 & 1 \\ 15 & -2 \end{bmatrix}, \quad \tilde{y} = \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

Try $y(t) = x e^{\lambda t}$, $x = \begin{pmatrix} u \\ v \end{pmatrix} \neq \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

$$(\Rightarrow \tilde{y}'(t) = \lambda \tilde{x} e^{\lambda t})$$

$$(*) \Rightarrow \lambda \tilde{x} e^{\lambda t} = A \tilde{x} e^{\lambda t}$$

$$\Rightarrow A \tilde{x} = \lambda \tilde{x}$$

$$\Rightarrow (A - \lambda I) \tilde{x} = \underline{0}$$

$$I = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

i.e. $\begin{bmatrix} 0 - \lambda & 1 \\ 15 & -2 - \lambda \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

(3.2)

But the equation $B\underline{x} = \underline{0}$
has a nonzero solution $\underline{x} \neq \underline{0}$
if and only if the matrix B is
singular (has no inverse B^{-1})

(see if B^{-1} did exist, could do
 $B\underline{x} = \underline{0} \Rightarrow \underbrace{B^{-1}B}_{=I} \underline{x} = B^{-1}\underline{0} \Rightarrow \underline{x} = \underline{0}$)

But the condition for B to be singular
is $\det(B) = 0$ (See K §4.0)

Since we are only interested in nonzero
solutions $\underline{x} \neq \underline{0}$ of $(A - \lambda I)\underline{x} = \underline{0}$, we
must require

$$\det(A - \lambda I) = 0$$

Eigenvalue
condition
(or equation)
for A

3.3

$$\text{So } \begin{vmatrix} 0-\lambda & 1 \\ 15 & -2-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (-\lambda)(-2-\lambda) - 15 = 0$$

$$\Rightarrow \lambda^2 + 2\lambda - 15 = 0 \quad (\text{charac. quadratic!})$$

$$\Rightarrow (\lambda + 5)(\lambda - 3) = 0$$

$$\Rightarrow \lambda_1 = 3, \quad \lambda_2 = -5$$

So the roots of the characteristic quadratic now appear as the eigenvalues of A.

Eigenvalues are $\lambda_1 = 3, \lambda_2 = -5$

(3.4)

Finding e'vectors: $\lambda_1 = 3$:

||
(2.14)

$$(A - 3I)\underline{x} = \underline{0}$$

$$\Rightarrow \begin{bmatrix} 0-3 & 1 \\ 15 & -2-3 \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{cases} -3u + v = 0 \\ 15u - 5v = 0 \end{cases} \Rightarrow v = 3u$$

Choosing $u = 1$, e'vector is $\underline{x}^{(1)} = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$

$\lambda_2 = -5$:

$$(A + 5I)\underline{x} = \underline{0}$$

$$\Rightarrow \begin{bmatrix} 5 & 1 \\ 15 & 3 \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow \begin{cases} 5u + v = 0 \\ 15u + 3v = 0 \end{cases} \Rightarrow v = -5u$$

Choosing $u = 1$, e'vector is $\underline{x}^{(2)} = \begin{pmatrix} 1 \\ -5 \end{pmatrix}$

So now know that $\underline{x}^{(1)}e^{3t}$ and $\underline{x}^{(2)}e^{-5t}$
are solutions.

$$\textcircled{3.5} = \textcircled{2.15}$$

Then general solution is

$$\underline{y}(t) = \alpha \underline{x}^{(1)} e^{3t} + \beta \underline{x}^{(2)} e^{-5t}$$

$$\text{i.e. } \begin{pmatrix} y_1(t) \\ y_2(t) \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 3 \end{pmatrix} e^{3t} + \beta \begin{pmatrix} 1 \\ -5 \end{pmatrix} e^{-5t}$$

[Recall $y(t) = y_1(t)$ - top component
 $= \alpha e^{3t} + \beta e^{-5t}$ - as before

$$\text{Also } \underline{y_2(t) = y'(t) = 3\alpha e^{3t} - 5\beta e^{-5t}}$$

With IC, $y(0) = -1 \Rightarrow y_1(0) = -1$
 $y'(0) = 13 \Rightarrow y_2(0) = 13$

we get

$$y(0) = \begin{pmatrix} -1 \\ 13 \end{pmatrix} = \alpha \begin{pmatrix} 1 \\ 3 \end{pmatrix} + \beta \begin{pmatrix} 1 \\ -5 \end{pmatrix}$$

$$\Rightarrow \alpha = 1, \beta = -2 \quad \text{as before,}$$

So get unique solution:

$$\underline{\underline{y(t) = \underline{x}^{(1)} e^{3t} - 2 \underline{x}^{(2)} e^{-5t}}}$$

EX:

(3.6)

$$y''(t) + 4y(t) = 0$$

a) Directly:

Try $y(t) = e^{\lambda t}$

$$\Rightarrow (\lambda^2 + 4)e^{\lambda t} = 0$$

$$\Rightarrow \lambda = \pm 2i$$

General solution:

$$y(t) = Ae^{2it} + Be^{-2it}$$

Complex form

$$= A[\cos(2t) + i\sin(2t)]$$

$$+ B[\cos(2t) - i\sin(2t)]$$

$$= C\cos(2t) + D\sin(2t) \quad \underline{\text{real form}}$$

$$C = (A+B) \quad D = i(A-B)$$

Use ICs to fix A, B (or C, D)

b) As a system:

(3.7)

$$\text{Let } y_1 = y, \quad y_2 = y'$$

$$\begin{aligned} \text{Then get: } y_1' &= y' = y_2 \\ y_2' &= y'' = -4y = -4y_1 \end{aligned}$$

i.e.

$$\begin{pmatrix} y_1' \\ y_2' \end{pmatrix} = \begin{bmatrix} 0 & 1 \\ -4 & 0 \end{bmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

or

$$\underline{y}'(t) = A \underline{y}(t) \quad A = \begin{bmatrix} 0 & 1 \\ -4 & 0 \end{bmatrix}$$

$$\text{Try } \underline{y}(t) = \underline{x} e^{\lambda t} \quad (\Rightarrow y'(t) = \lambda \underline{x} e^{\lambda t})$$

$$\Rightarrow \lambda \underline{x} e^{\lambda t} = A \underline{x} e^{\lambda t}$$

$$\Rightarrow A \underline{x} = \lambda \underline{x} \quad \text{eigenvalue equation for } A$$

(3.8)

$$\text{So } (A - \lambda I)\underline{x} = \underline{0}$$

Eigenvalue condition:

$$0 = \det(A - \lambda I) = \begin{vmatrix} 0 - \lambda & 1 \\ -4 & 0 - \lambda \end{vmatrix}$$

$$= (-\lambda)(-\lambda) + 4$$

So

$$\lambda^2 + 4 = 0$$

$$\Rightarrow \lambda_1 = 2i, \quad \lambda_2 = -2i \quad \text{e'values}$$

Finding e'vectors: $\lambda_1 = 2i$:

$$(A - 2i I)\underline{x} = \underline{0}$$

$$\Rightarrow \begin{bmatrix} 0 - 2i & 1 \\ -4 & 0 - 2i \end{bmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

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$$\Rightarrow \left. \begin{array}{l} -2i u + v = 0 \\ -4u - 2iv = 0 \end{array} \right\} \Rightarrow v = 2iu$$

Choosing $u=1$ we get $\underline{x}^{(1)} = \begin{pmatrix} 1 \\ 2i \end{pmatrix}$

Similarly ($i \leftrightarrow -i$) $\underline{x}^{(2)} = \begin{pmatrix} 1 \\ -2i \end{pmatrix}$
corresponds to e'value $\lambda_2 = -2i$

Now have that each of $\underline{x}^{(1)} e^{2it}$ and $\underline{x}^{(2)} e^{-2it}$ is a solution, and general solution is:-

$$\underline{y}(t) = c_1 \underline{x}^{(1)} e^{2it} + c_2 \underline{x}^{(2)} e^{-2it}$$

$$= c_1 \begin{pmatrix} 1 \\ 2i \end{pmatrix} e^{2it} + c_2 \begin{pmatrix} 1 \\ -2i \end{pmatrix} e^{-2it}$$

general solution in
complex form

(3.10)

Getting general solution in real form:

$$\begin{aligned}
 \underline{y(t)} &= \begin{pmatrix} c_1 [\cos(2t) + i \sin(2t)] \\ 2i c_1 [\cos(2t) + i \sin(2t)] \end{pmatrix} \\
 &+ \begin{pmatrix} c_2 [\cos(2t) - i \sin(2t)] \\ -2i c_2 [\cos(2t) - i \sin(2t)] \end{pmatrix} \\
 &= \begin{pmatrix} (c_1 + c_2) \cos(2t) + i (c_1 - c_2) \sin(2t) \\ -2(c_1 + c_2) \sin(2t) + 2i (c_1 - c_2) \cos(2t) \end{pmatrix} \\
 &= d_1 \begin{pmatrix} \cos(2t) \\ -2 \sin(2t) \end{pmatrix} + d_2 \begin{pmatrix} \sin(2t) \\ 2 \cos(2t) \end{pmatrix}
 \end{aligned}$$

where $d_1 = c_1 + c_2$, $d_2 = i(c_1 - c_2)$

Fix d_1, d_2 (or c_1, c_2) using ICs.

A general system of n coupled (3.11)
1st order ODEs has:

n unknowns $y_1(t), y_2(t), \dots, y_n(t)$
satisfying equations of the form:

$$\left. \begin{aligned} y_1'(t) &= f_1(t, y_1(t), y_2(t), \dots, y_n(t)) \\ y_2'(t) &= f_2(t, y_1(t), y_2(t), \dots, y_n(t)) \\ &\vdots \\ y_n'(t) &= f_n(t, y_1(t), y_2(t), \dots, y_n(t)) \end{aligned} \right\} (3.1)$$

where

$f_1, f_2, f_3, \dots, f_n$ are given.

OR, equivalently:

$$\underline{\underline{y}}'(t) = \underline{\underline{F}}(t, \underline{\underline{y}}(t)) \quad \text{where}$$

$$\underline{\underline{y}}(t) = \begin{pmatrix} y_1(t) \\ y_2(t) \\ \vdots \\ y_n(t) \end{pmatrix}, \quad \underline{\underline{F}}(t, \underline{\underline{y}}(t)) = \begin{pmatrix} f_1(t, \underline{\underline{y}}(t)) \\ f_2(t, \underline{\underline{y}}(t)) \\ \vdots \\ f_n(t, \underline{\underline{y}}(t)) \end{pmatrix}$$

(3.12)

A solution for $a < t < b$ has the form

$$y_1(t) = h_1(t), \quad y_2(t) = h_2(t), \quad \dots, \quad y_n(t) = h_n(t)$$

where $h_1, h_2, \dots, h_n$ are functions that are once-differentiable, for $a < t < b$.

i.e.

$$\underline{y}(t) = \underline{h}(t), \quad \underline{h} = \begin{pmatrix} h_1 \\ h_2 \\ \vdots \\ h_n \end{pmatrix}$$

A typical initial-value problem (IVP) consists of (**) plus ICs at some t_0 :

$$y_1(t_0) = K_1, \quad y_2(t_0) = K_2, \quad \dots, \quad y_n(t_0) = K_n$$

$$(3.2) \quad \underline{y}(t_0) = \underline{K}, \quad \underline{K} = \begin{pmatrix} K_1 \\ K_2 \\ \vdots \\ K_n \end{pmatrix} \quad \begin{matrix} \text{(constant} \\ \text{vector} \\ \text{-given)} \end{matrix}$$

(3-13)

Here we can suppose $a < t_0 < b$,
and we are only interested in the
solution for $t_0 \leq t < b$

For such an IVP, there exists a
unique solution, provided the
functions $f_1, f_2, \dots, f_n$ are suitably
smooth.

(See K p. ~~137~~¹³⁷ Theorem 1)

You do not need to know the Theorem,
but you should know that things
can go wrong if the f 's are
not nice!

(3.14)

Summary:

~~K: 3.0, 3.1~~ K: 4.0, 4.1

1) Know how to solve 2nd order, linear ODE with constant coefficients in two ways:

a) Directly

b) By converting to a system, then finding e-values and e-vectors.

2) In case that e-values are complex

a) know how to use $(i \leftrightarrow -i)$ trick to save work.

b) know how to go from complex form to real form of solution

3) Read and understand nature of existence + uniqueness Theorem 1, K p. ~~134~~