

# Assignment 2

## MATH 7502 - Semester 2, 2018

### Mathematics for Data Science 1

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#### Question 1

(a) Find the general solutions of the system whose augmented matrix is given by

$$\begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ -1 & 7 & -4 & 2 & 7 \end{bmatrix}.$$

(b) Under what condition on  $b_1, b_2, b_3$  is this system solvable?

$$\begin{aligned} x + 2y - 2z &= b_1 \\ 2x + 5y - 4z &= b_2 \\ 4x + 9y - 8z &= b_3. \end{aligned}$$

(c) Give an example of an inconsistent undetermined system of two equations with three unknowns.

#### Question 2

(a) Let  $v_1 = \begin{bmatrix} 1 \\ 0 \\ -2 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} -3 \\ 1 \\ 8 \end{bmatrix}$ , and  $y = \begin{bmatrix} h \\ -5 \\ -3 \end{bmatrix}$ . For what value(s) of  $h$  is  $y$  in the plane spanned by  $v_1$  and  $v_2$ .

(b) Explain why  $\left\{ \begin{bmatrix} 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \end{bmatrix} \right\}$  is a basis for  $\mathbb{R}^2$  (Hint: Write  $e_1$  and  $e_2$  as linear combinations of these vectors.)

(c) Find three different bases for the column space of  $U = \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \end{bmatrix}$ . Then find two different bases for the row space of  $U$ .

#### Question 3

Consider the transformation  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  that projects vectors onto the line  $l = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$ ,  $t \in \mathbb{R}$

(a) Find a formula for  $T\left(\begin{bmatrix} x \\ y \\ z \end{bmatrix}\right)$ , and prove that  $T$  is a linear transformation.

(b) Find matrix  $A$ , associated with  $T$ .

(c) Determine the relationship between the row space of  $A$   $\text{row}(A)$  and the line  $l$ .

(d) Determine the null space,  $\text{Null}(A)$ .

#### Question 4

(a) Define  $A = \begin{bmatrix} 0 & 1 \\ 2 & 1 \end{bmatrix}$ , Find the eigenvalues and associated eigenvectors of  $A$ .

(b) Can you represent  $\begin{bmatrix} 8 \\ 10 \end{bmatrix}$  as a linear combination of the eigenvectors? If so, do so.

(c) Consider the linear transformation  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  where  $T(v) = Av$ . Suppose  $n$  is a positive integer and we write  $T^n : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  for the composition of  $T$  with itself  $n$  times. Use your answer in (a) and (b) to calculate

$$T^{47}\left(\begin{bmatrix} 8 \\ 10 \end{bmatrix}\right)$$

#### Question 5

Suppose we have matrices  $A, B, X$ , and  $Y$  with  $AX = BY$ .

(a) Give an example showing that  $A \neq 0$  is not enough to conclude that  $X = Y$ .

(b) Show that if  $A$  is left-invertible, we can conclude from  $AX = AY$  that  $X = Y$ .

(c) Show that if  $A$  is not left-invertible, there are matrices  $X$  and  $Y$  with  $X \neq Y$ , and  $AX = AY$ .

#### Question 6

Consider the stacked vectors

$$c_1 = \begin{bmatrix} a_1 \\ b_1 \end{bmatrix}, \dots, c_k = \begin{bmatrix} a_k \\ b_k \end{bmatrix}.$$

where  $a_1, \dots, a_k$  are  $n$ -vectors and  $b_1, \dots, b_k$  are  $m$ -vectors. For each case, either prove or provide a counter example.

(a) Suppose  $a_1, \dots, a_k$  are linearly independent (we make no assumptions about  $b_1, \dots, b_k$ ). Can we conclude that the stacked vectors  $c_1, \dots, c_k$  are linearly independent?

(b) Suppose  $a_1, \dots, a_k$  are linearly dependent (we make no assumptions about  $b_1, \dots, b_k$ ). Can we conclude that the stacked vectors  $c_1, \dots, c_k$  are linearly dependent?

## Question 7

Let  $G \in \mathbb{R}^{m \times n}$  represent a contignecy matrix of  $m$  students who are members of  $n$  groups with

$$G_{ij} = \begin{cases} 1 & \text{student } i \text{ is in group } j \\ 0 & \text{student } i \text{ is not in group } j \end{cases}$$

(a) What is the meaning of the 3rd column of  $G$ ?

(b) What is the meaning of the 2nd row of  $G$ ?

(c) Give a simple formula for the  $n$ -vectors  $M$ , where  $M_i$  is the total membership in the group  $i$ .

(d) Interpret  $(GG^T)_{ij}$  in simple English.

(e) Interpret  $(G^T G)_{ij}$  in simple English.

## Question 8

An  $n$ -vector  $x$  is symmetric if  $x_k = x_{n-k+1}$  for  $k = 1, \dots, n$ . It is anti-symmetric if  $x_k = -x_{n-k+1}$  for  $k = 1, \dots, n$ .

(a) Show that every vector  $x$  can be decomposed in a unique way as sum  $x = x_s + x_a$  of a symmetric vector  $x_s$  and an anti-symmetric vector  $x_a$ .

(b) Show that the symmetric and anti-symmetric parts  $x_s$  and  $x_a$  are linear functions of  $x$ . Given matrices  $A_s$  and  $A_a$  such that  $x_s = A_s x$ , and  $x_a = A_a x$  for all  $x$ .

## Question 9

For descriptions of  $y$  below, express it as  $y = Ax$  for some  $A$  (You should specify  $A$ ).

(a)  $y_i$  is the difference between  $x_i$  and the average of  $x_1, \dots, x_{i-1}$ . (We take  $y_1 = x_1$ ).

(b)  $y_i$  is the difference between  $x_i$  and the average value of all other  $x_j$ . i.e the average of  $x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_n$

## Question 10

Write your own code to implement the Gram-Schmidt procedure. Test your code and find an orthogonal basis of

$$\left\{ \begin{bmatrix} 1 \\ 2 \\ 3 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

## Question 11

The following code generates a signal together with noise.

- Compute and plot the Fourier transform of the signal without noise.
- Compute and plot the Fourier transform with signal noise.
- Corrupt the signal with different white-noise, and reproduce the plot of (a) and (b).

In [1]:

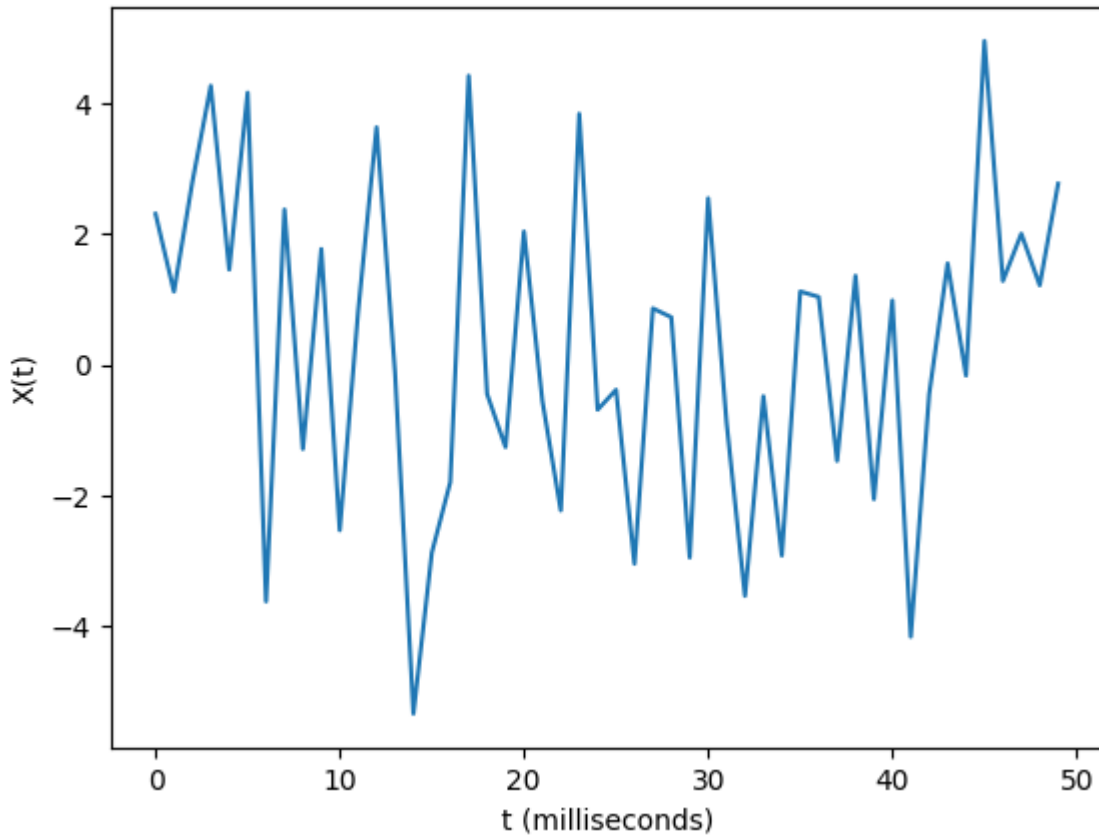
```
using PyPlot

Fs = 1000;           #Sampling frequency
T = 1/Fs;           #Sampling period
L = 1500;           #Length of signal
t = (0:L-1)*T;      #Time vector

#Form a signal containing a 25 Hz sinusoid of amplitude 0.9 and a 120 Hz sinusoid of amplitude 1.
S = 0.9*sin.(2*pi*25*t) + sin.(2*pi*120*t);
#Corrupt the signal with zero-mean white noise with a variance of 4.
X = S+2*randn(size(t));

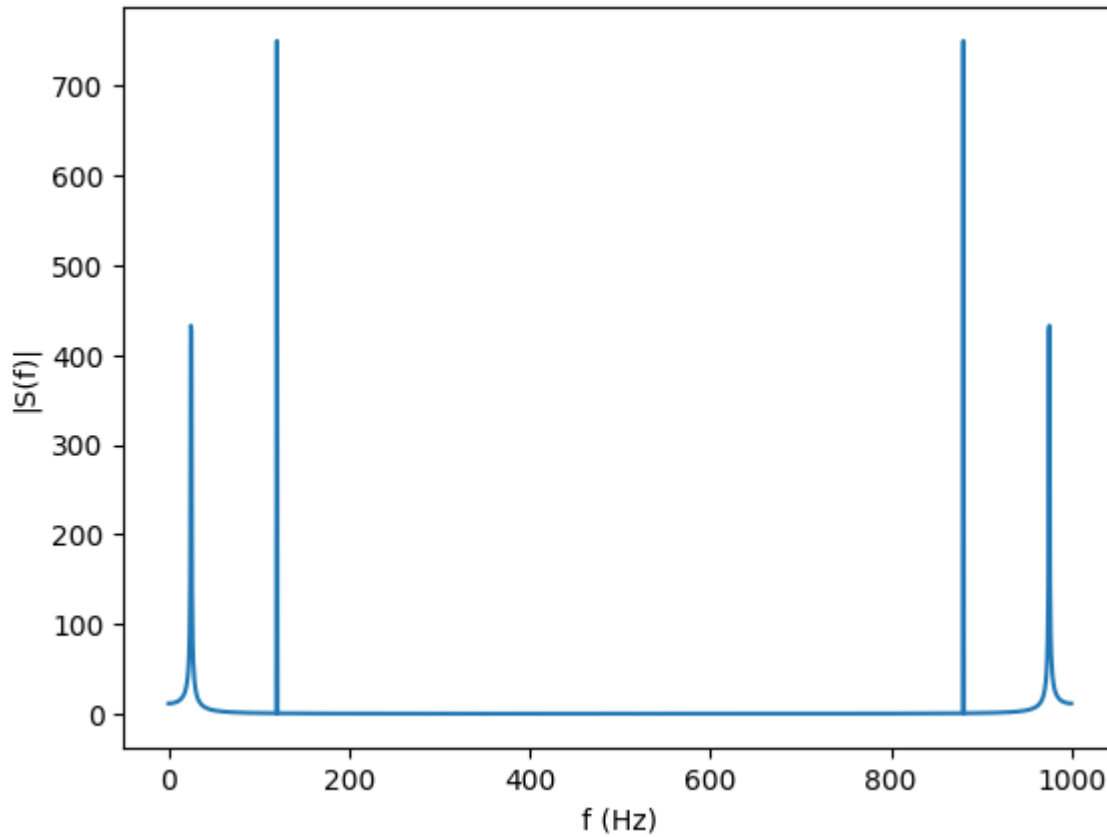
plot(1000*t[1:50],X[1:50])
title("Signal Corrupted with Zero-Mean Random Noise")
xlabel("t (milliseconds)")
ylabel("X(t)");
```

Signal Corrupted with Zero-Mean Random Noise



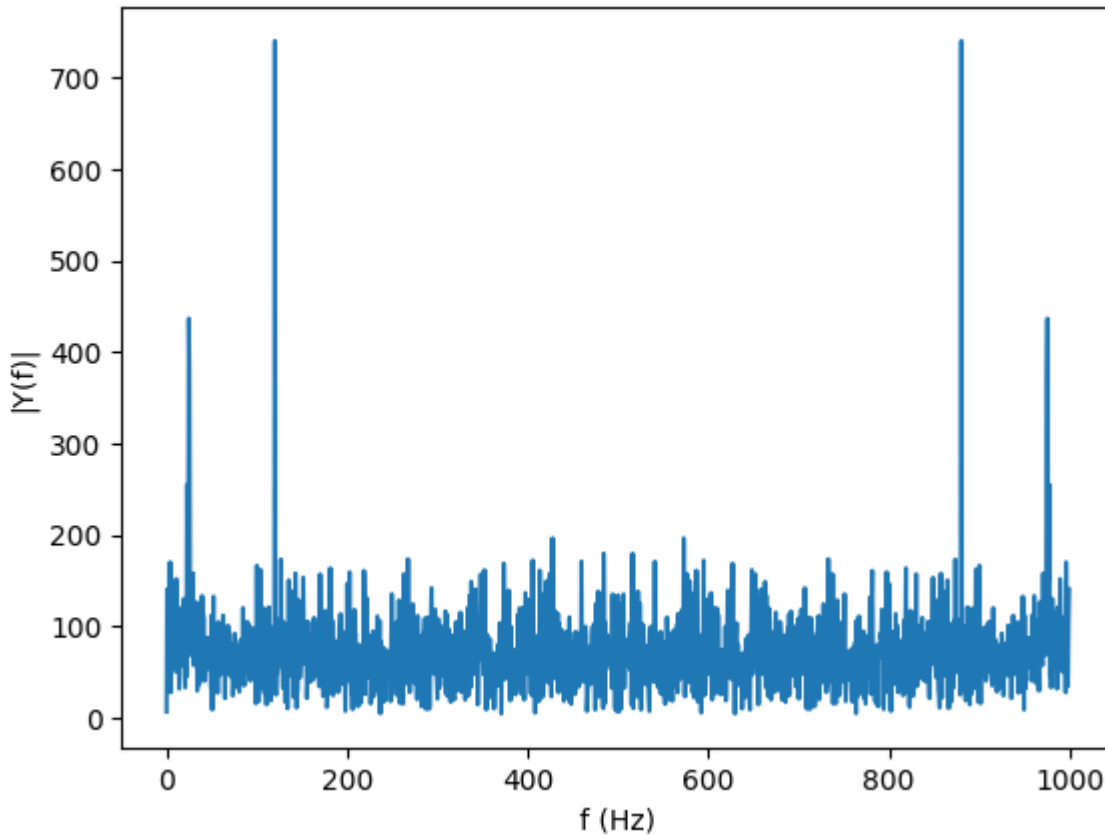
In [2]:

```
## Compute the FFT for the term without noise
Z=abs(fft(S))
## frequency axis
f = Fs*(0:(L-1))/L;
plot(f,Z)
xlabel("f (Hz)")
ylabel("|S(f)|");
```



In [3]:

```
## Compute the FFT for the term without noise
Y=abs(fft(X))
## frequency axis
f = Fs*(0:(L-1))/L;
plot(f,Y)
xlabel("f (Hz)")
ylabel("|Y(f)|");
```



## Question 12

Explain the results of the previous question. How can Fourier analysis be used in data science? Present a 1-2 paragraph subjective description.