

# Solution to Assignment 2

MATH7502 2019, Semester 2

[Assignment 2 questions \(https://courses.smp.uq.edu.au/MATH7502/2019/ass2.pdf\)](https://courses.smp.uq.edu.au/MATH7502/2019/ass2.pdf)

## Solution to Question 1

We have,

$$x = \sum_{i=1}^k \beta_i a_i$$

with  $a_i$  orthonormal vectors.

$$\|x\|^2 = \|\beta_1 a_1 + \dots + \beta_k a_k\|^2 = (\beta_1 a_1 + \dots + \beta_k a_k)^T (\beta_1 a_1 + \dots + \beta_k a_k) = \beta_1^2 + \dots + \beta_k^2 = \|\beta\|^2.$$

Hence  $\|x\| = \|\beta\|$ .

## Solution to Question 2

We have

$$a_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad a_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \quad \dots \quad a_n = \begin{bmatrix} 1 \\ 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix},$$

(a) Running Gram-Schmidt

$$q_1 = \tilde{q}_1 = a_1 = e_1$$

$$q_2 = \tilde{q}_2 = a_2 - (q_1^T a_2) q_1 = e_2$$

$$q_3 = \tilde{q}_3 = a_3 - (q_1^T a_3) q_1 - (q_2^T a_3) q_2 = e_3$$

$\vdots$

$$q_n = e_n$$

(b) Yes,  $a_1, \dots, a_n$  is a basis for  $\mathbb{R}^n$ . Because G-S didn't terminate, we found that the vectors are linearly independent and there are  $n$  of them.

(c) A G-S implementation

```

In [32]: 1 using LinearAlgebra
          2
          3 function gs(a)
          4     k, n = length(a), length(a[1])
          5     q = fill(zeros(n),k) #an array of vectors
          6     q[1] = a[1]/norm(a[1])
          7     for i in 2:k
          8         qT = a[i]-sum([(q[j]'*a[i])*q[j] for j in 1:i-1])
          9         if norm(qT) < 10^-8
         10             println("Dependent vectors after $(i) iterations")
         11             return
         12         end
         13         q[i] = qT/norm(qT)
         14     end
         15     q
         16 end

```

Out[32]: gs (generic function with 1 method)

### Test it on some basic inputs...

```
In [33]: 1 q = gs([[1,1],[1,0]])
```

Out[33]: 2-element Array{Array{Float64,1},1}:  
 [0.707107, 0.707107]  
 [0.707107, -0.707107]

```
In [34]: 1 norm.(q)
```

Out[34]: 2-element Array{Float64,1}:  
 0.9999999999999999  
 1.0

```
In [35]: 1 q[1]'*q[2]
```

Out[35]: 2.7755575615628914e-16

```
In [44]: 1 q = gs([rand(20) for _ in 1:15]);
         2 norm.(q)
```

```
Out[44]: 15-element Array{Float64,1}:
0.9999999999999999
1.0
0.9999999999999999
0.9999999999999999
1.0
1.0
0.9999999999999999
0.9999999999999999
1.0000000000000002
0.9999999999999999
0.9999999999999999
1.0
0.9999999999999999
0.9999999999999999
1.0
```

```
In [45]: 1 Q = hcat(q...)
         2 Q'*Q
```

```
Out[45]: 15x15 Array{Float64,2}:
 1.0          1.17229e-16  2.87541e-16  ...  6.12258e-16  1.80411e-16
 1.17229e-16  1.0          -2.5431e-16  ... -2.95635e-16  5.96745e-16
 2.87541e-16 -2.5431e-16  1.0          ... -1.47594e-16 -6.245e-17
 7.13624e-17 -1.03405e-16 -6.06927e-17 ... -3.29407e-16  4.44089e-16
-2.91614e-16 -3.53699e-16 -3.64357e-16 ... -4.12128e-16 -4.78784e-15
-1.5689e-17  -1.24718e-16  4.85177e-17  ...  9.88694e-16  1.72085e-15
 2.70461e-17  2.09903e-16  1.70043e-16  ...  2.62886e-16  4.23273e-15
-9.19821e-17  4.30837e-16  -1.07332e-16 ...  1.43942e-15  5.02376e-15
 4.29366e-16  2.1304e-16  -1.17614e-16 ... -2.53108e-16  9.85323e-16
-7.24987e-16 -3.84805e-16 -6.40421e-16 ...  2.18725e-15 -4.996e-15
-3.70411e-16 -5.16291e-17 -7.1818e-16  ...  1.94999e-15  5.7454e-15
 1.0265e-15  -2.7893e-16  -1.1588e-16  ... -2.57221e-15 -2.13718e-15
 6.16813e-17 -8.80087e-17  2.64214e-16 ... -9.35483e-16 -9.58627e-16
 6.12258e-16 -2.95635e-16 -1.47594e-16 ... 1.0          -1.17938e-14
 1.80411e-16  5.96745e-16 -6.245e-17   ... -1.17938e-14  1.0
```

```
In [47]: 1 q = gs([rand(20) for _ in 1:30]);
```

Dependent vectors after 21 iterations

### Now for the question

```
In [48]: 1 a(k,n) = [ones(k) ; zeros(n-k)]
          2
          3 n = 10
          4 vecs = [a(k,n) for k in 1:n]
          5 gs(vecs)
```

```
Out[48]: 10-element Array{Array{Float64,1},1}:
 [1.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 1.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 1.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 1.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 1.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 1.0]
```



## Now shuffle the order

```
In [54]: 1 using Random
          2 Random.seed!(0)
          3 n = 10
          4 vecs = shuffle([a(k,n) for k in 1:n])
          5 gs(vecs)
```

```
Out[54]: 10-element Array{Array{Float64,1},1}:
 [0.353553, 0.353553, 0.353553, 0.353553, 0.353553, 0.353553, 0.353553,
 0.353553, 0.0, 0.0]
 [0.612372, 0.612372, -0.204124, -0.204124, -0.204124, -0.204124, -0.2041
 24, -0.204124, 0.0, 0.0]
 [0.0, 0.0, 0.408248, 0.408248, 0.408248, -0.408248, -0.408248, -0.40824
 8, 0.0, 0.0]
 [0.0, 0.0, 0.408248, 0.408248, -0.816497, 1.35974e-16, 1.35974e-16, 1.35
 974e-16, 0.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.408248, 0.408248, -0.816497, 0.0, 0.0]
 [0.0, 0.0, 1.11022e-16, 1.11022e-16, 2.22045e-16, -2.22045e-16, -2.22045
 e-16, 1.9984e-15, 1.0, 0.0]
 [0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, 0.0, -1.9984e-15, 1.0]
 [0.0, 0.0, 1.57009e-16, 1.57009e-16, -3.14018e-16, 0.707107, -0.707107,
 7.85046e-16, -3.14018e-16, 0.0]
 [0.0, 0.0, 0.707107, -0.707107, -7.85046e-17, -1.57009e-16, 1.57009e-16,
 -4.61935e-31, -1.57009e-16, 0.0]
 [0.707107, -0.707107, 3.92523e-17, 3.92523e-17, 3.92523e-17, 3.92523e-1
 7, 3.92523e-17, 3.92523e-17, 0.0, 0.0]
```

```
In [55]: 1 vecs[1]
```

```
Out[55]: 10-element Array{Float64,1}:
 1.0
 1.0
 1.0
 1.0
 1.0
 1.0
 1.0
 1.0
 1.0
 0.0
 0.0
```

As appears, a different order of input yields a different set of vectors. Here for example, the first vector was  $e_8$  and thus it was normalized... The rest of the results were very different

## Solution to Question 3

$A$  and  $B$  are matrices of the same dimension.

(a) If  $Ax = Bx$  holds for all vectors  $x$  then  $A = B$ . This is because we can use  $x = e_i$  for all  $i$  and this shows that the  $i$ 'th column of  $A$  is the same as that of  $B$ .

(b) If  $Ax = Bx$  for some non zero vector it doesn't imply that  $A = B$ . Take for example  $x = [1 \ 1]^T$  with,

$$A = [1 \ 0], \quad B = [0 \ 1].$$

## Solution to Question 4

$A \in \mathbb{R}^{m \times n}$ . We want to show that  $A$  has the same null-space as  $A^T A$  (a matrix in  $\mathbb{R}^{n \times n}$ ). Define, the null-spaces of  $A$  and  $A^T A$  respectively as,

$$\mathcal{N}_1 = \{x \in \mathbb{R}^n \mid Ax = 0_m\} \quad \mathcal{N}_2 = \{x \in \mathbb{R}^n \mid A^T Ax = 0_n\}.$$

Take  $x \in \mathcal{N}_1$ . Then  $Ax = 0_m$ . Left multiply by  $A^T$  then  $A^T Ax = 0_n$ . Hence  $x \in \mathcal{N}_2$ . Hence  $\mathcal{N}_1 \subset \mathcal{N}_2$ .

Take now  $x \in \mathcal{N}_2$ . Then  $A^T Ax = 0_n$ . Left multiply by  $x^T$ :

$$x^T A^T Ax = 0$$

or

$$(Ax)^T Ax = 0$$

Hence  $\|Ax\|^2 = 0$  and  $\|Ax\| = 0$ . Hence  $Ax$  must be the zero vector, that is  $Ax = 0_m$ . Hence  $x \in \mathcal{N}_1$ . Hence  $\mathcal{N}_2 \subset \mathcal{N}_1$ .

Since  $\mathcal{N}_1 \subset \mathcal{N}_2$  and  $\mathcal{N}_2 \subset \mathcal{N}_1$ , we have that  $\mathcal{N}_1 = \mathcal{N}_2$ .

## Solution to Question 5

$$A^T = -A$$

(a) For a  $2 \times 2$  matrix:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}.$$

We have  $a = -a$ ,  $d = -d$  and  $b = -c$ . This implies that  $a$  and  $d$  must be zero and there is a single number  $\alpha$  with

$$A = \begin{bmatrix} 0 & \alpha \\ -\alpha & 0 \end{bmatrix}.$$

(b) In general we must have that  $A_{ii} = -A_{ii}$  hence  $A_{ii} = 0$  (diagonal elements are 0).

(c) Assume  $A^T = -A$ :

$$(Ax)^T x = x^T A^T x = -(x^T Ax) = -((Ax)^T x)$$

Hence the inner product must be 0 and  $Ax$  is orthogonal to  $x$ .

(d) Now assume  $(Ax)^T x = 0$  for any vector  $x$ . That is  $x^T A^T x = 0$ . Hence,

$$x^T A^T x = 0,$$

or taking transpose of the scalar,

$$x^T A x = 0.$$

That is,

$$\sum_{k=1}^n \sum_{\ell=1}^n x_k x_\ell A_{k\ell} = 0.$$

If we set  $x = e_i$  for some  $i$  we get that  $A_{ii} = 0$ .

Now if we set  $x = e_i + e_j$  for  $i \neq j$  then

$$(e_i + e_j)^T A (e_i + e_j) = e_i^T A e_i + e_i^T A e_j + e_j^T A e_i + e_j^T A e_j = 0$$

or,

$$A_{ii} + A_{ij} + A_{ji} + A_{jj} = 0.$$

Since we already showed that  $A_{ii}$  and  $A_{jj}$  are 0 we get  $A_{ij} = -A_{ji}$  and hence  $A = -A^T$ .

(e) Take any square matrix  $\tilde{A}$  and look at  $A = \tilde{A} - \tilde{A}^T$ . Observe that it is skew-symmetric since  $A^T = -A$

In [110]:

```
1 function randSkewSym(n)
2     A = rand(n,n)
3     A-A'
4 end
5
6 innerProds = []
7
8 for _ in 1:10^5
9     A = randSkewSym(5)
10    x = rand(5)
11    push!(innerProds,dot(A*x,x))
12 end
13 minimum(innerProds),maximum(innerProds)
```

Out[110]: (-5.551115123125783e-16, 6.661338147750939e-16)

We see above that all inner products were "0"

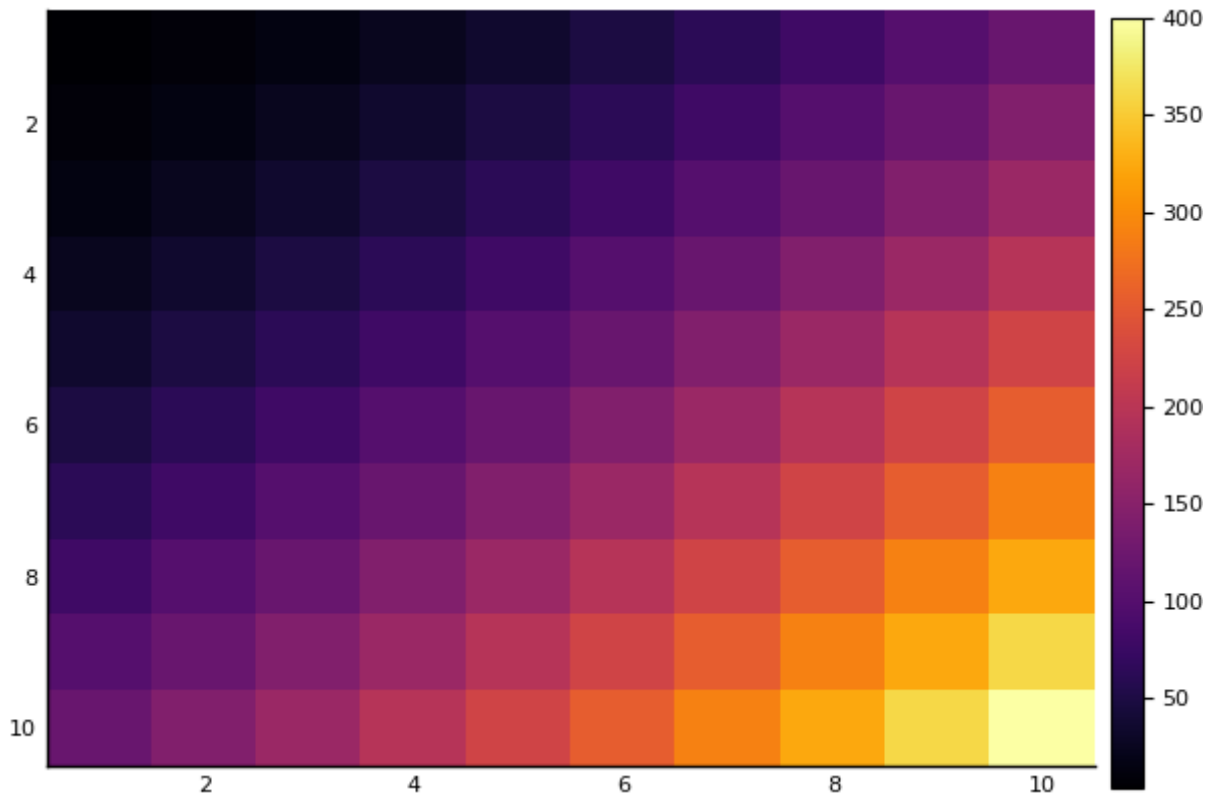
## Solution to Question 6

Note: Important in this question to find the **matrix of the linear transformation**



```
In [173]: 1 using Plots
          2 pyplot()
          3 N = 10
          4 image = [(i+j)^2 for i in 1:N, j in 1:N]
          5 heatmap(image,yflip = true)
```

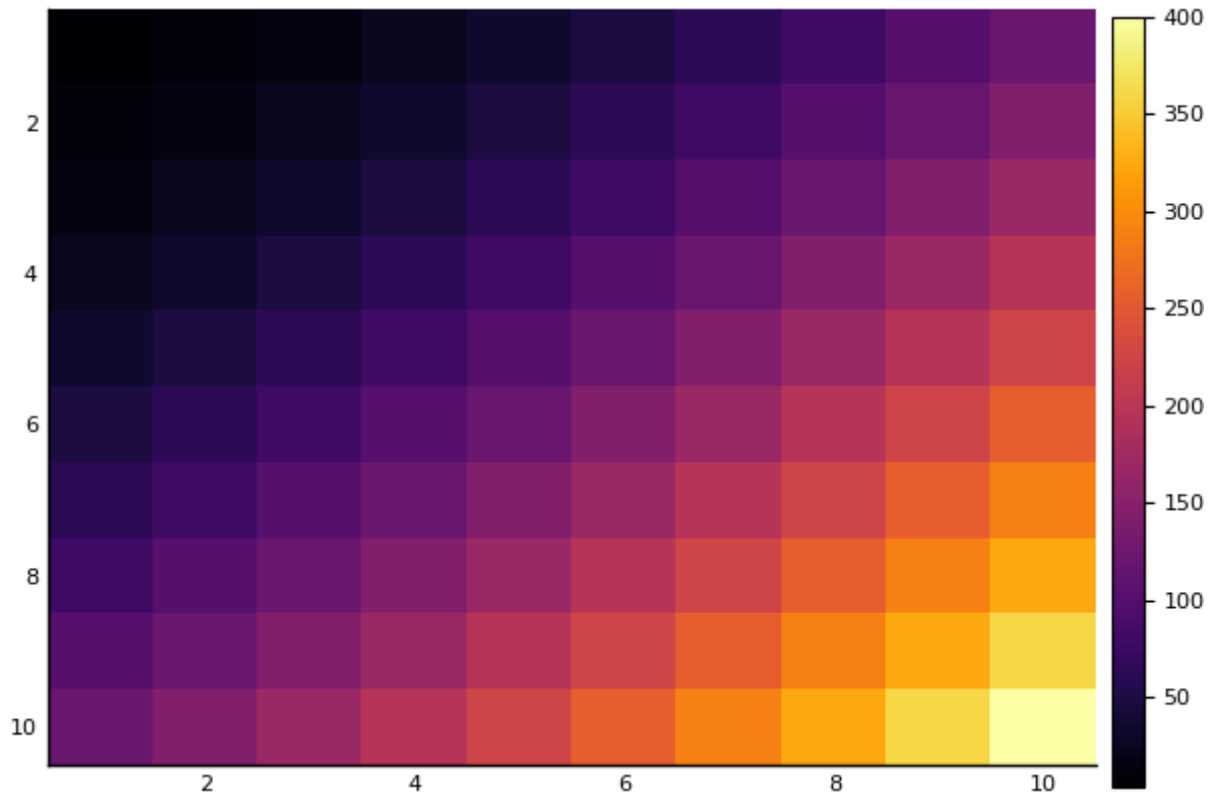
Out[173]:



Functions from changing image to vector and back

```
In [174]: 1 img2Vec(img) = vcat([img[:,j] for j in 1:N]...)
          2 vec2Img(vec) = reshape(vec,N,N)
          3 heatmap(vec2Img(img2Vec(image)),yflip = true) #test
```

Out[174]:



```
In [175]: 1 #The key to solving the problem is to work with identity vectors
          2 ee(i) = [j ==i ? 1 : 0 for j in 1:N^2]
```

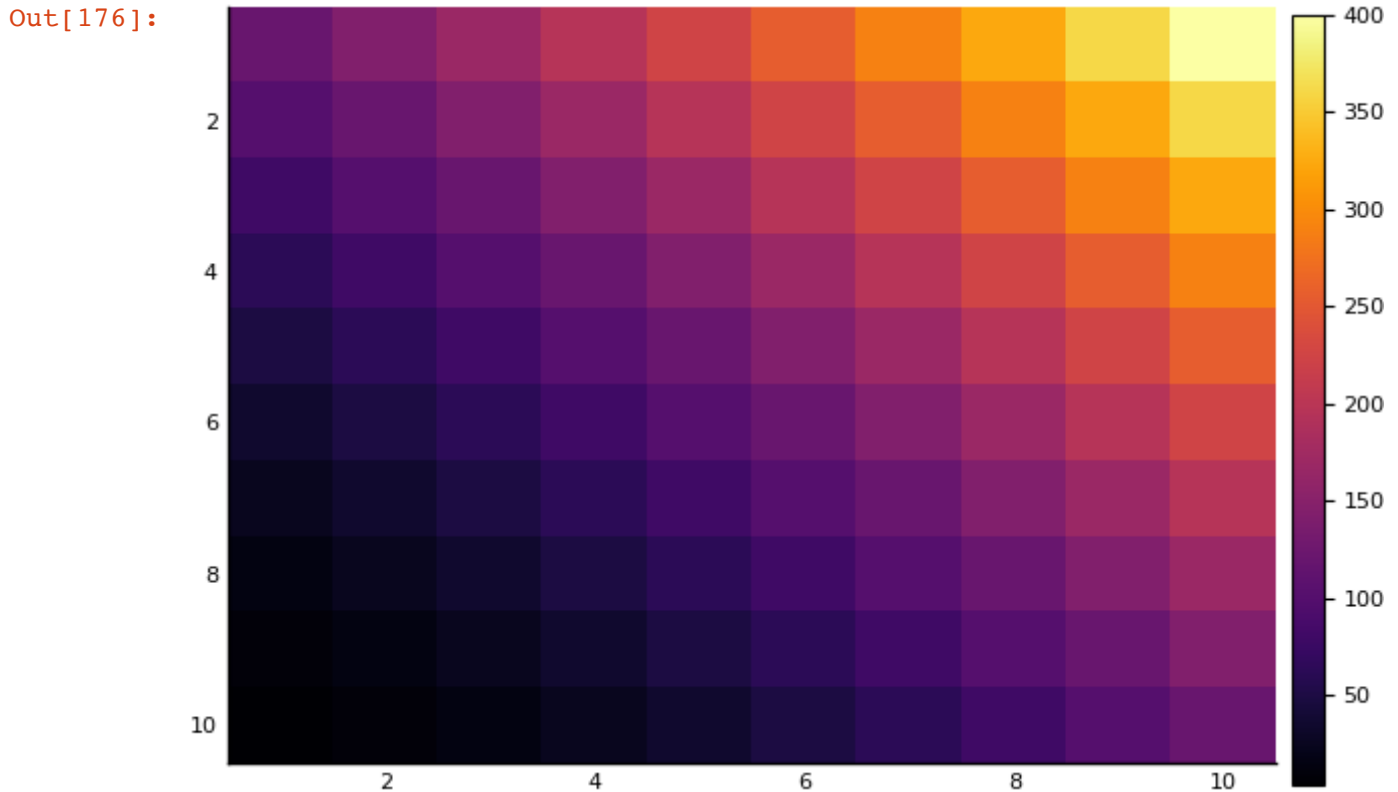
Out[175]: ee (generic function with 1 method)

(a) Turning the original image upside down.

```

In [176]: 1 #This is the function for flipping the image (without thinking about matrices)
          2 flipImageUpDown(img) = [img[i,j] for j in N:-1:1, i in 1:N]
          3
          4 #testIt
          5 heatmap(
          6     flipImageUpDown(image),
          7     yflip = true)

```



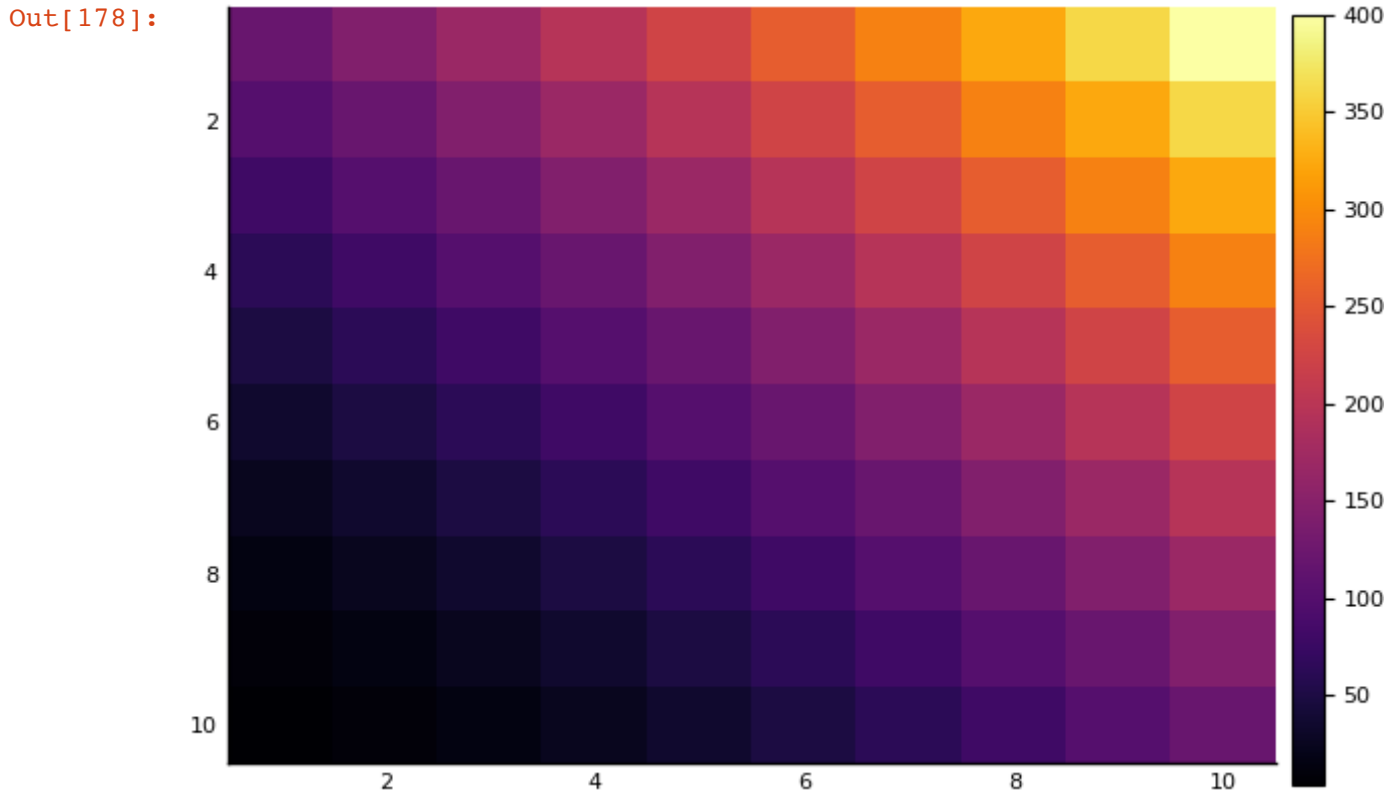
**HOWEVER:** The above isn't what we asked for. We wanted the **MATRIX** that does it... Here it is:

We get it by assuming the transformation is linear and applying it to the vectors  $e_1, \dots, e_{N^2} \dots$



Testing it:

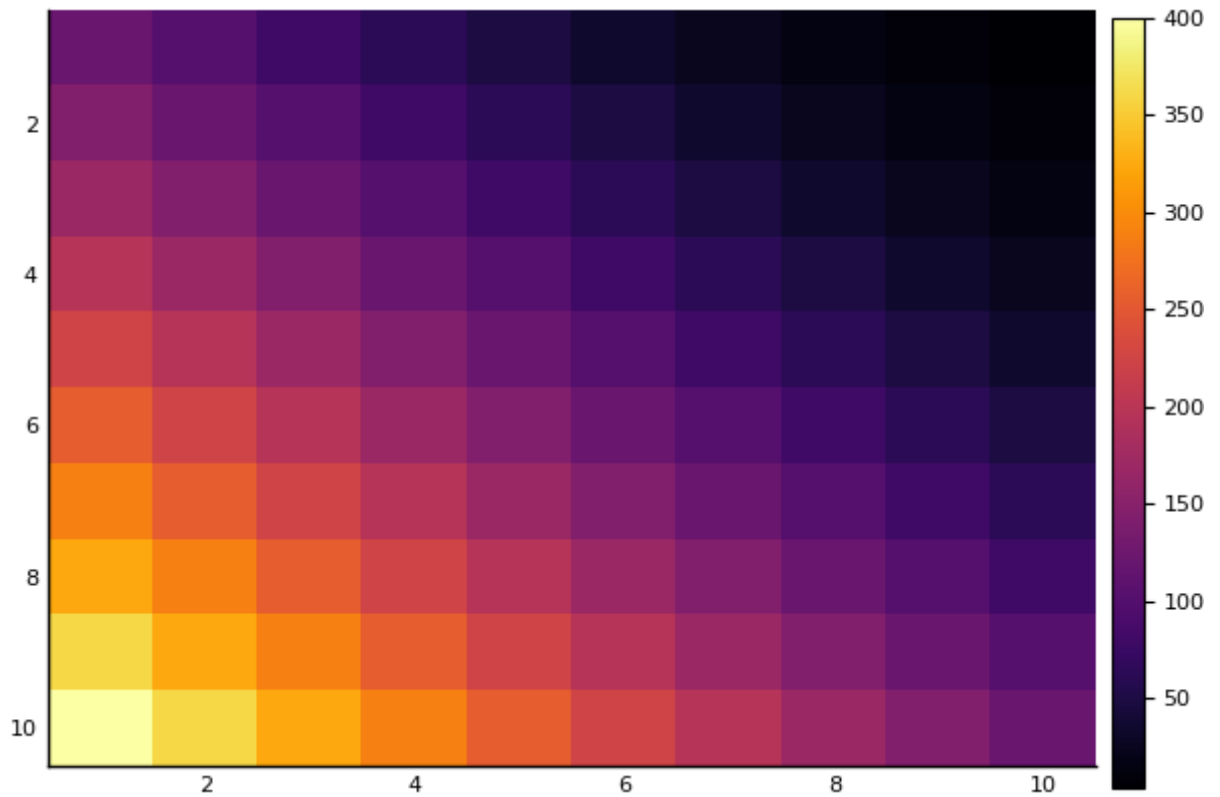
```
In [178]: 1 heatmap(  
2     vec2Img(  
3         Aflip*img2Vec(image)  
4     ),  
5     yflip = true)
```



(a) Rotate the original image clockwise 90 degrees

```
In [179]: 1 #This is the function for it (without thinking about matrix multiplicat.
2
3 rotateClockWise90(img) = [img[i,j] for j in 1:N, i in N:-1:1]
4
5 #testIt
6 heatmap(
7     rotateClockWise90(image),
8     yflip = true)
```

Out[179]:



In [180]:

```
1 #We can do: (this is just like before only with the rotateClockWise90 fu
2 #Arotate = hcat([img2Vec(rotateClockWise90(vec2Img(ee(i)))) for i in 1:l
3
4 #instead later make a function that gives us the linear transformation o
5
6 makeA(trans) = hcat([img2Vec(trans(vec2Img(ee(i)))) for i in 1:N^2]...)
7
8 #Now
9 Arotate = makeA(rotateClockWise90)
```

Out[180]: 100×100 Array{Int64,2}:

```
0 0 0 0 0 0 0 0 0 0 1 0 0 0 ... 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 ... 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 1 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 1
0 0 0 0 0 0 0 0 0 1 0 0 0 0 ... 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 ... 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 ... 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
```

```

0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0
0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0
0 0

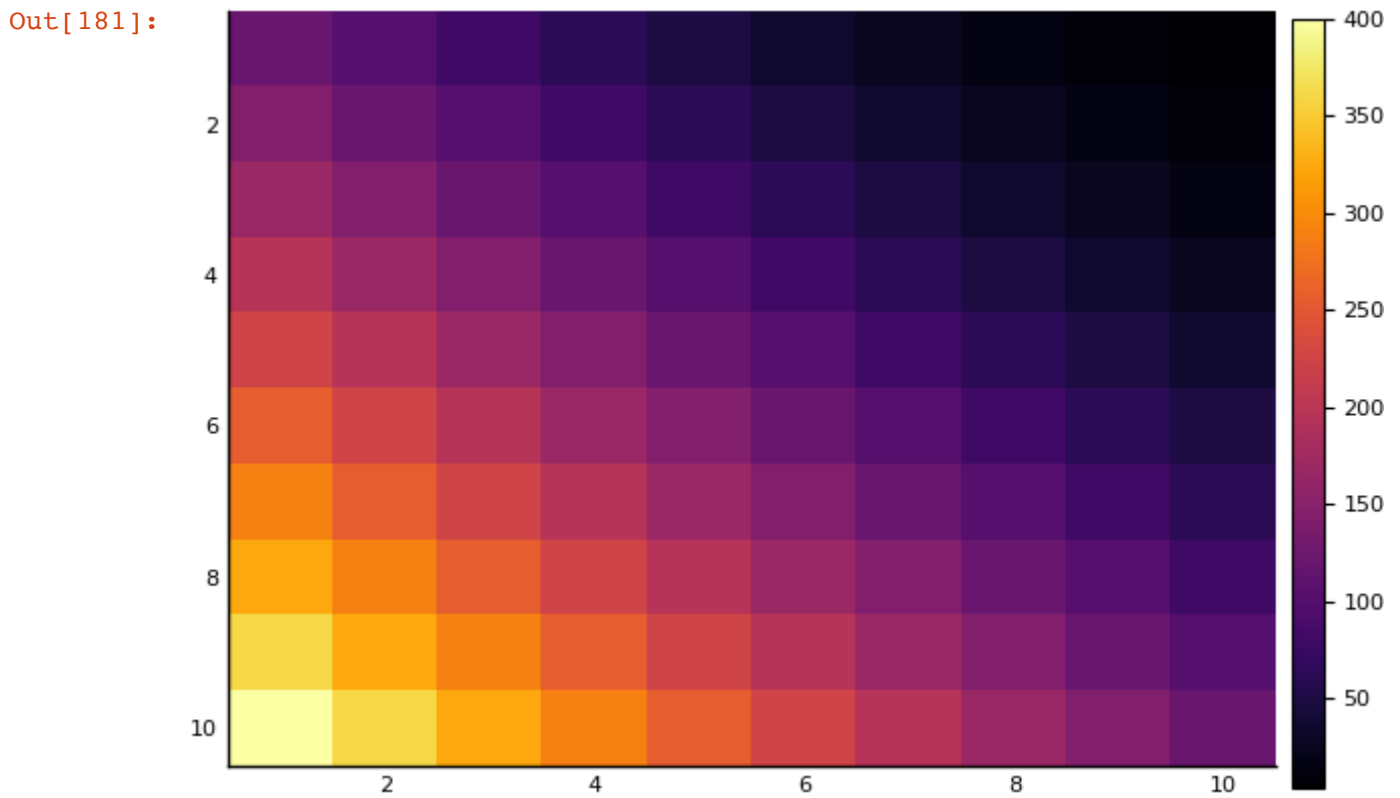
```

**Testing it:**

```

In [181]: 1 heatmap(
          2     vec2Img(
          3         Arotate*img2Vec(image)
          4     ),
          5     yflip = true)

```



(c) Translate up and 2 right by 2 pixels...

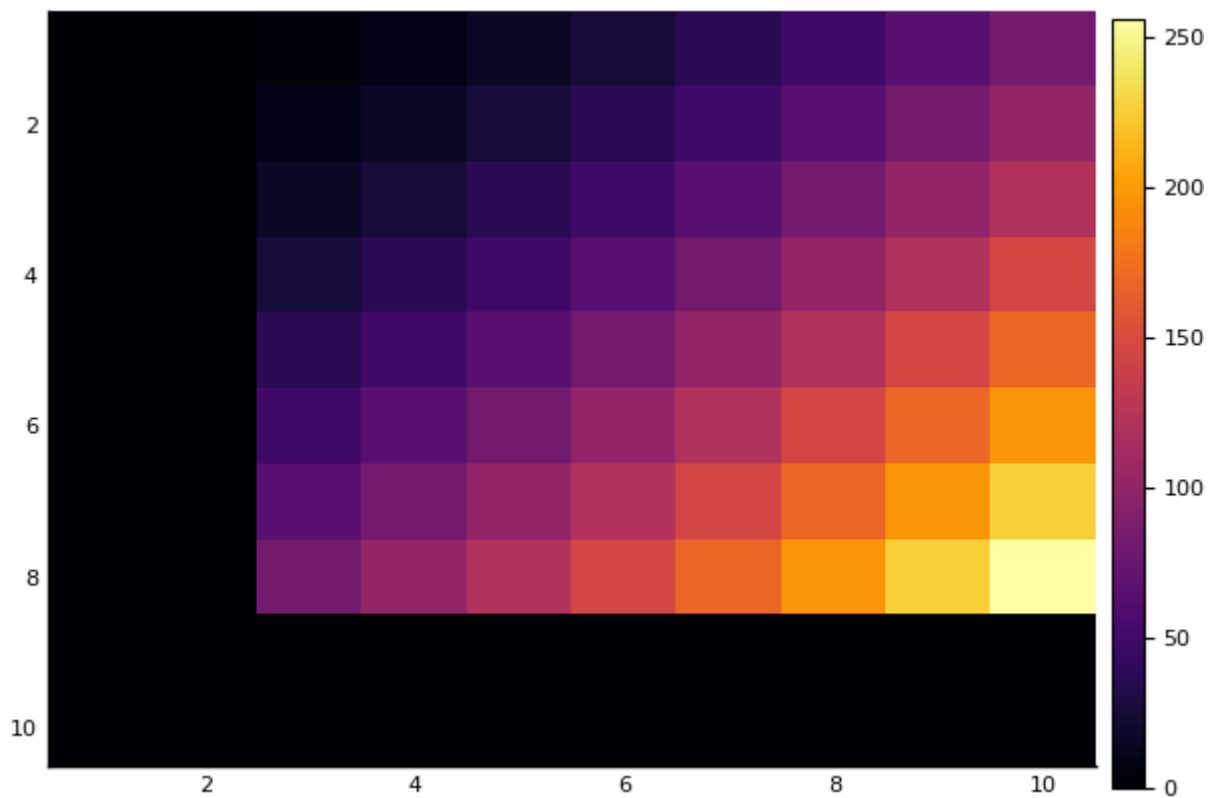


```

In [198]: 1 #This is the function for it (without thinking about matrix multiplicat.
2
3 function translateUpRight(img)
4     outImage = zeros(N,N)
5     for i in 1:N-2
6         for j in 3:N
7             outImage[i,j] = img[i,j-2]
8         end
9     end
10    outImage
11 end
12
13 #testIt
14 heatmap(
15     translateUpRight(image),
16     yflip = true) #note the heatmap renormalizes the colours...

```

Out[198]:



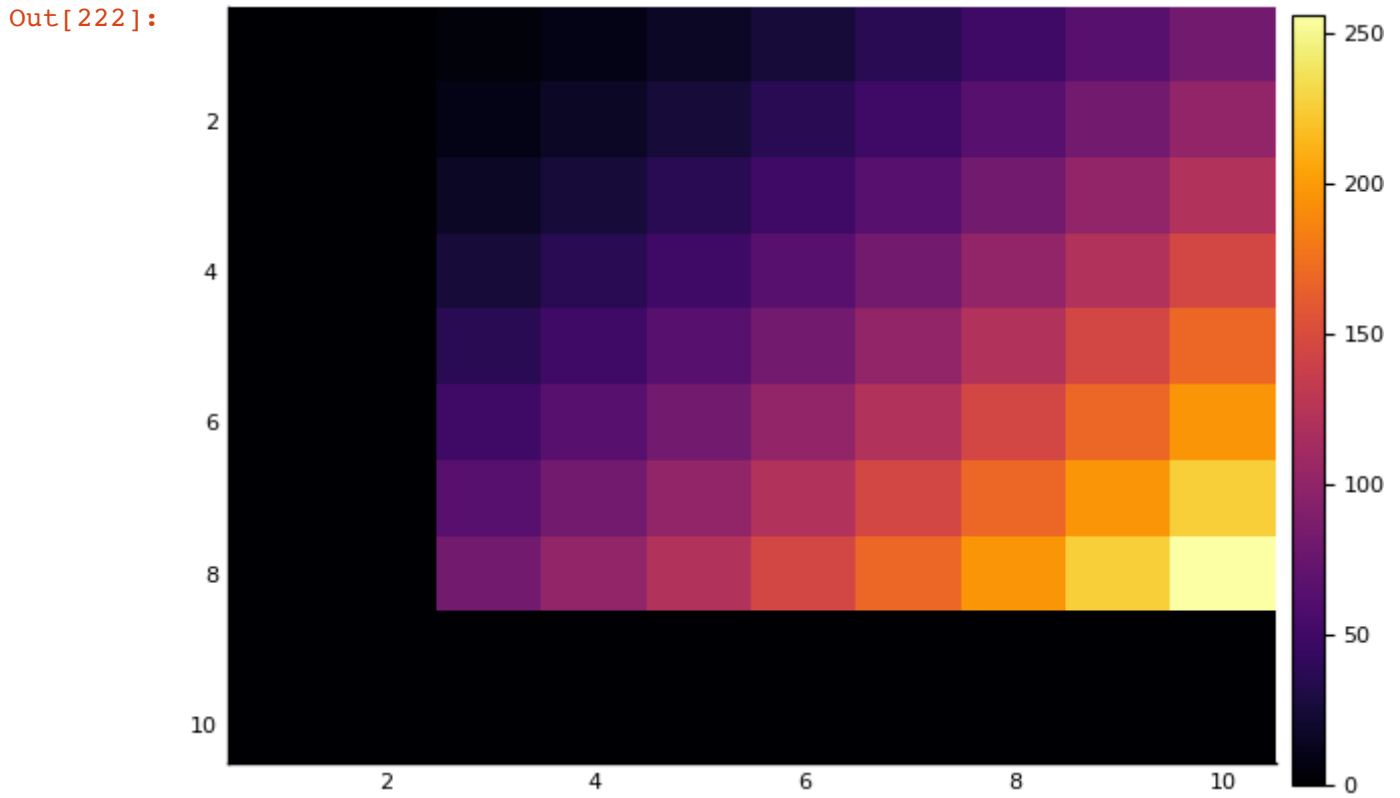
```
In [199]: 1 translateUpRight(image)
```

```
Out[199]: 10x10 Array{Float64,2}:  
 0.0  0.0   4.0   9.0  16.0  25.0  36.0  49.0  64.0  81.0  
 0.0  0.0   9.0  16.0  25.0  36.0  49.0  64.0  81.0 100.0  
 0.0  0.0  16.0  25.0  36.0  49.0  64.0  81.0 100.0 121.0  
 0.0  0.0  25.0  36.0  49.0  64.0  81.0 100.0 121.0 144.0  
 0.0  0.0  36.0  49.0  64.0  81.0 100.0 121.0 144.0 169.0  
 0.0  0.0  49.0  64.0  81.0 100.0 121.0 144.0 169.0 196.0  
 0.0  0.0  64.0  81.0 100.0 121.0 144.0 169.0 196.0 225.0  
 0.0  0.0  81.0 100.0 121.0 144.0 169.0 196.0 225.0 256.0  
 0.0  0.0   0.0   0.0   0.0   0.0   0.0   0.0   0.0   0.0  
 0.0  0.0   0.0   0.0   0.0   0.0   0.0   0.0   0.0   0.0
```



Testing it:

```
In [222]: 1 heatmap(  
2     vec2Img(  
3         Atranslate*img2Vec(image)  
4     ),  
5     yflip = true)
```

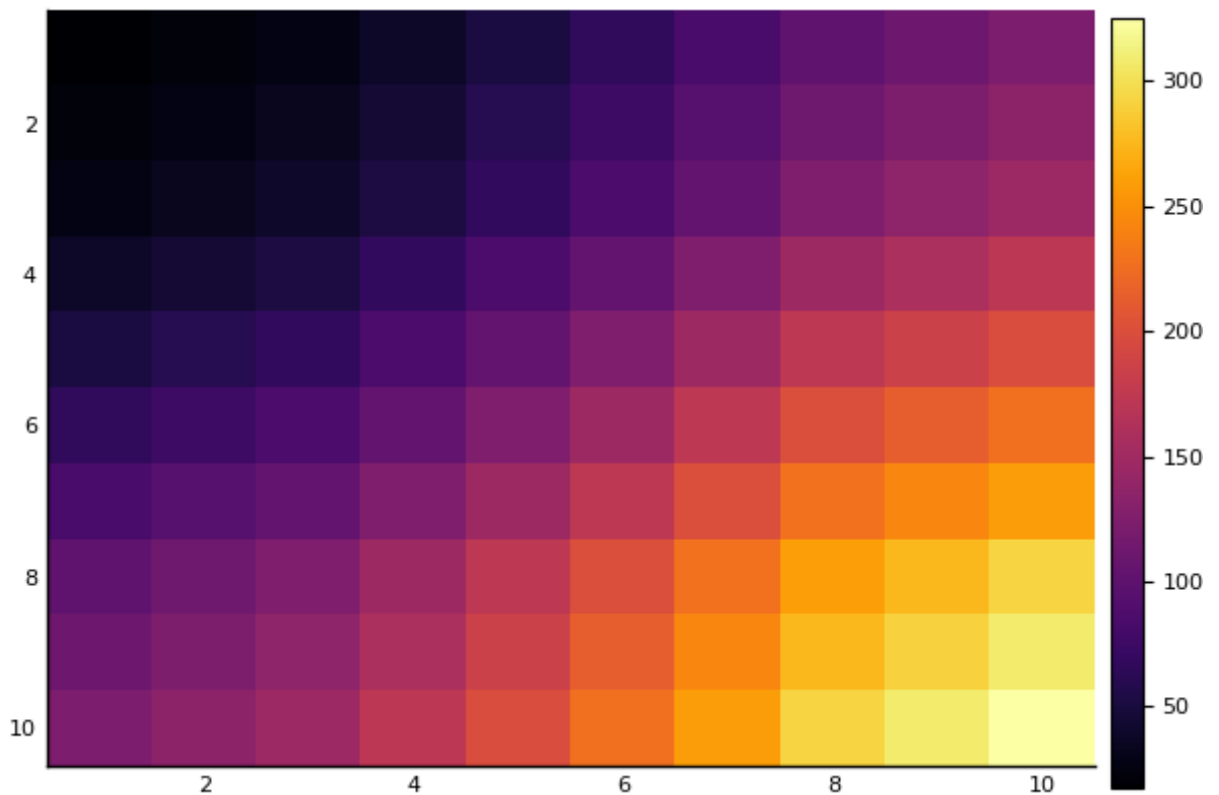


(d) Smooth (average of pixels)

In [229]:

```
1 using Statistics
2
3 m1(i) = max(i,1)
4 mN(i) = min(i,N)
5
6 d = 2
7
8 #This is the function for it (without thinking about matrix multiplicat.
9 #It takes the average of the neighbouring d cells in each direction m1(
10 function smooth(img)
11     outImage = zeros(N,N)
12     for i in 1:N
13         for j in 1:N
14             outImage[i,j] = mean(img[m1(i-d):mN(i+d),m1(j-d):mN(j+d)])
15         end
16     end
17     outImage
18 end
19
20 #testIt
21 heatmap(
22     smooth(image),
23     yflip = true) #note the heatmap renormalizes the colours...
```

Out[229]:



**Note image looks the same, but slightly different**

```
In [228]: 1 image
```

```
Out[228]: 10×10 Array{Int64,2}:
```

```
 4  9  16  25  36  49  64  81  100  121
 9  16  25  36  49  64  81  100  121  144
16  25  36  49  64  81  100  121  144  169
25  36  49  64  81  100  121  144  169  196
36  49  64  81  100  121  144  169  196  225
49  64  81  100  121  144  169  196  225  256
64  81  100  121  144  169  196  225  256  289
81  100  121  144  169  196  225  256  289  324
100 121  144  169  196  225  256  289  324  361
121 144  169  196  225  256  289  324  361  400
```

```
In [227]: 1 smooth(image)
```

```
Out[227]: 10×10 Array{Float64,2}:
```

```
17.3333  22.1667  27.6667  ...  83.6667  102.667  112.167  122.333
22.1667  27.5     33.5     ...  93.5     113.5    123.5    134.167
27.6667  33.5     40.0     ...  104.0    125.0    135.5    146.667
38.6667  45.5     53.0     ...  125.0    148.0    159.5    171.667
51.6667  59.5     68.0     ...  148.0    173.0    185.5    198.667
66.6667  75.5     85.0     ...  173.0    200.0    213.5    227.667
83.6667  93.5     104.0    ...  200.0    229.0    243.5    258.667
102.667  113.5    125.0    ...  229.0    260.0    275.5    291.667
112.167  123.5    135.5    ...  243.5    275.5    291.5    308.167
122.333  134.167  146.667  ...  258.667  291.667  308.167  325.333
```

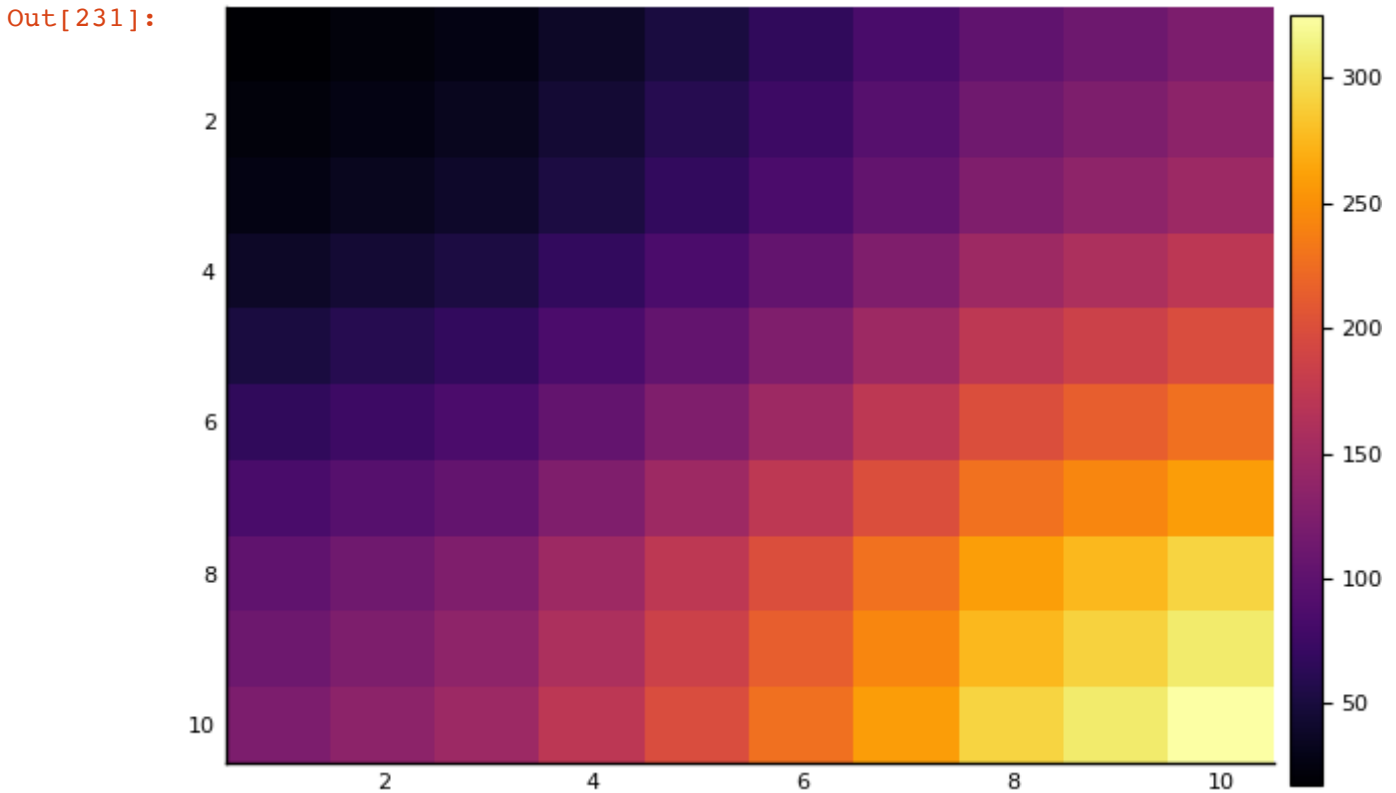
In [230]:

```
1 #this is then the linear transformation
2 Asmooth = makeA(smooth)
```

Out[230]:

```
100x100 Array{Float64,2}:
0.111111  0.111111  0.111111  ...  0.0      0.0      0.0
0.0833333 0.0833333 0.0833333  ...  0.0      0.0      0.0
0.0666667 0.0666667 0.0666667  ...  0.0      0.0      0.0
0.0        0.0666667 0.0666667  ...  0.0      0.0      0.0
0.0        0.0        0.0666667  ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0833333 0.0833333 0.0833333  ...  0.0      0.0      0.0
0.0625    0.0625    0.0625     ...  0.0      0.0      0.0
0.05      0.05      0.05       ...  0.0      0.0      0.0
⋮
0.0        0.0        0.0          ⋮      0.0625    0.0625    0.0625
0.0        0.0        0.0          ⋮      0.0833333 0.0833333 0.0833333
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0      0.0      0.0
0.0        0.0        0.0          ...  0.0666667 0.0        0.0
0.0        0.0        0.0          ...  0.0666667 0.0666667 0.0
0.0        0.0        0.0          ...  0.0666667 0.0666667 0.0666667
0.0        0.0        0.0          ...  0.0833333 0.0833333 0.0833333
0.0        0.0        0.0          ...  0.111111  0.111111  0.111111
```

```
In [231]: 1 heatmap(
2         vec2Img(
3           Asmooth*img2Vec(image)
4         ),
5         yflip = true)
```



```
In [232]: 1 vec2Img(
2           Asmooth*img2Vec(image)
3         )
```

Out[232]: 10x10 Array{Float64,2}:

17.3333	22.1667	27.6667	...	83.6667	102.667	112.167	122.333
22.1667	27.5	33.5	...	93.5	113.5	123.5	134.167
27.6667	33.5	40.0	...	104.0	125.0	135.5	146.667
38.6667	45.5	53.0	...	125.0	148.0	159.5	171.667
51.6667	59.5	68.0	...	148.0	173.0	185.5	198.667
66.6667	75.5	85.0	...	173.0	200.0	213.5	227.667
83.6667	93.5	104.0	...	200.0	229.0	243.5	258.667
102.667	113.5	125.0	...	229.0	260.0	275.5	291.667
112.167	123.5	135.5	...	243.5	275.5	291.5	308.167
122.333	134.167	146.667	...	258.667	291.667	308.167	325.333

## Solution to Question 7

$$f : [-1, 1] \rightarrow \mathbb{R} \quad \alpha = \int_{-1}^1 f(x) dx.$$

$$\hat{\alpha} = w_1 f(t_1) + \dots + w_n f(t_n)$$



(a) Take  $f(\cdot)$  is a polynomial of degree  $d$ :

$$f(x) = \beta_0 + \beta_1 x + \dots + \beta_d x^d$$

Hence in this case,

$$\alpha = \beta_0 x \Big|_{-1}^1 + \beta_1 \frac{1}{2} x^2 \Big|_{-1}^1 + \beta_2 \frac{1}{3} x^3 \Big|_{-1}^1 + \dots + \beta_d \frac{1}{d+1} x^{d+1} \Big|_{-1}^1 = 2 \left( \beta_0 + \frac{1}{3} \beta_2 + \frac{1}{5} \beta_4 + \dots \right)$$

Now

$$\hat{\alpha} = (w_1 + \dots + w_n) \beta_0 + (w_1 t_1 + \dots + w_n t_n) \beta_1 + (w_1 t_1^2 + \dots + w_n t_n^2) \beta_2 + \dots$$

We can now equate coefficients of  $\alpha$  and  $\hat{\alpha}$  to get the system of equations  $Ax = b$  where  $A$  is  $(d+1) \times n$ :

$$\begin{bmatrix} 1 & 1 & \dots & 1 \\ t_1 & t_2 & \dots & t_n \\ t_1^2 & t_2^2 & \dots & t_n^2 \\ \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots \\ \vdots & \vdots & & \vdots \\ t_1^d & t_2^d & \dots & t_n^d \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ \vdots \\ \vdots \\ \vdots \\ w_n \end{bmatrix} = 2 \begin{bmatrix} 1 \\ 0 \\ 1/3 \\ 0 \\ 1/5 \\ 0 \\ \vdots \end{bmatrix}$$

## Here is a little demonstration that it works...

In [46]:

```
1 using Random
2 Random.seed!(0)
3 f(x) = 6 + 34x + 9x^2 - 5x^3 + 0.2x^4 + 3x^5
4 d = 5
5 δ = 0.00001
6 alpha = sum([f(x)*δ for x in -1:δ:1])
```

Out[46]: 18.08015200031334

In [47]:

```
1 n = 6;
2 ts = sort(2*rand(n).-1) # some arbitrary t values
3
4 A = [ts[j]^i for i in 0:d, j in 1:n]
```

Out[47]:

```
6×6 Array{Float64,2}:
 1.0      1.0      1.0      1.0      1.0      1.0
-0.670868 -0.645342 -0.593047 -0.44224  0.647295  0.820713
 0.450064  0.416467  0.351705  0.195576  0.418991  0.67357
-0.301934 -0.268764 -0.208577 -0.0864915 0.271211  0.552808
 0.202558  0.173445  0.123696  0.03825  0.175553  0.453696
-0.13589  -0.111931 -0.0733576 -0.0169157 0.113635  0.372355
```

```
In [48]: 1 b = 2*[(i%2)/i for i in 1:d+1]
```

```
Out[48]: 6-element Array{Float64,1}:
 2.0
 0.0
 0.6666666666666666
 0.0
 0.4
 0.0
```

```
In [49]: 1 w = A \ b
```

```
Out[49]: 6-element Array{Float64,1}:
-69.86735359420322
131.08788006208087
-71.2221609271108
11.313909446190433
 0.4283850586230596
 0.2593399544196729
```

```
In [50]: 1 w'*f.(ts)
```

```
Out[50]: 18.080000000000176
```

(b) and (c): Considering different rules:

(i) Trapezoid rule  $n = 2$   $t_1 = -1, t_2 = 1, w_1 = w_2 = 1/2$

$d = 1$  so  $A$  is  $2 \times 2$ :

$$A = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}.$$

Now  $b = [2 \ 0]^T$  and we need to see that  $w = [1/2 \ 1/2]^T$  satisfies  $Aw = b$ .

But it **doesn't** there was a mistake in the problem. It should have been  $w_1 = w_2 = 1$ .

```
In [54]: 1 A = [1 1; -1 1]; b = [2,0];
 2 w = [1,1]
 3 A*w - b
```

```
Out[54]: 2-element Array{Int64,1}:
 0
 0
```

```
In [92]: 1 f(x) = x != 0 ? sin(x)/x : 1 #can't evaluate sin(x)/x at x = 0, however
 2 δ = 0.000001
 3 alpha = sum([f(x)*δ for x in -1:δ:1])
```

```
Out[92]: 1.8921669822053007
```

```
In [74]: 1 ts = [-1,1]; w=[1,1]
         2 alphaHat = w'*f.(ts)
```

Out[74]: 1.682941969615793

So we get  $\hat{\alpha} = 1.6829$  vs.  $\alpha = 1.8921$

(ii) Simpson's rule

```
In [75]: 1 ts = [-1,0,1]; w = [1/3, 4/3, 1/3];
         2 d = 2; n = 3;
         3 A = [ts[j]^i for i in 0:d, j in 1:n]
```

Out[75]: 3×3 Array{Int64,2}:  
 1 1 1  
-1 0 1  
 1 0 1

```
In [76]: 1 b = 2*[(i%2)/i for i in 1:d+1]
```

Out[76]: 3-element Array{Float64,1}:  
 2.0  
 0.0  
 0.6666666666666666

**Now see it satisfies  $Aw = b$ . So yes it is order  $d = 2$**

```
In [77]: 1 A*w - b
```

Out[77]: 3-element Array{Float64,1}:  
-2.220446049250313e-16  
 0.0  
 0.0

```
In [78]: 1 alphaHat = w'*f.(ts)
```

Out[78]: 1.8943139898719308

So we get  $\hat{\alpha} = 1.8943$  vs.  $\alpha = 1.8921$ .

(ii) Simpson's 3/8 rule

```
In [81]: 1 ts = [-1, -1/3, 1/3, 1]; w = [1/4, 3/4, 3/4, 1/4];
         2 d = 3; n = 4;
         3 A = [ts[j]^i for i in 0:d, j in 1:n]
```

Out[81]: 4×4 Array{Float64,2}:  
 1.0 1.0 1.0 1.0  
-1.0 -0.333333 0.333333 1.0  
 1.0 0.111111 0.111111 1.0  
-1.0 -0.037037 0.037037 1.0

Now see it satisfies  $Aw = b$ . So yes it is order  $d = 3$

```
In [83]: 1 b = 2*[(i%2)/i for i in 1:d+1]
```

```
Out[83]: 4-element Array{Float64,1}:
 2.0
 0.0
 0.6666666666666666
 0.0
```

```
In [84]: 1 A*w - b
```

```
Out[84]: 4-element Array{Float64,1}:
 0.0
 -1.3877787807814457e-17
 0.0
 0.0
```

```
In [85]: 1 alphaHat = w'*f.(ts)
```

```
Out[85]: 1.8931116279866331
```

So we get  $\hat{\alpha} = 1.8931$  vs.  $\alpha = 1.8921$ .

(d) Let's get even closer with an order 4 rule that we find

```
In [90]: 1 d = 4;
 2 n = 5;
 3 ts = [-1,-1/2,0,1/2,1] #just some sensible grid
 4 A = [ts[j]^i for i in 0:d, j in 1:n]
```

```
Out[90]: 5x5 Array{Float64,2}:
 1.0  1.0  1.0  1.0  1.0
 -1.0 -0.5  0.0  0.5  1.0
 1.0  0.25  0.0  0.25  1.0
 -1.0 -0.125  0.0  0.125  1.0
 1.0  0.0625  0.0  0.0625  1.0
```

```
In [88]: 1 b = 2*[(i%2)/i for i in 1:d+1]
```

```
Out[88]: 5-element Array{Float64,1}:
 2.0
 0.0
 0.6666666666666666
 0.0
 0.4
```

So these are our weights:

```
In [89]: 1 w = A \ b
```

```
Out[89]: 5-element Array{Float64,1}:  
 0.155555555555555545  
 0.71111111111111117  
 0.26666666666666662  
 0.71111111111111111  
 0.15555555555555553
```

```
In [91]: 1 alphaHat = w'*f.(ts)
```

```
Out[91]: 1.892156949525523
```

So we get  $\hat{\alpha} = 1.8921569$  vs.  $\alpha = 1.8921669$ .

## Solution to Question 8

We want  $ab^T = ba^T$ . This means the matrix  $A = ab^T$ , is symmetric since  $A^T = (ab^T)^T = ba^T$ . Hence first we must have that  $a$  and  $b$  are of the same length.

Since we want  $A_{ij} = A_{ji}$  it means that

$$a_i b_j = a_j b_i.$$

If all of  $a = 0$  or  $b = 0$  this would hold immediately. However assume  $b \neq 0$  via  $b_i \neq 0$ . Now divide to get

$$\frac{a_j}{a_i} = \frac{b_j}{b_i}.$$

Hence the vectors  $a$  and  $b$  must have an angle of 0 between them.

A different (cleaner) way to arrive at this is via  $ab^T = ba^T$ . Left multiply by  $b^T$  and right multiply by  $a$ :

$$\begin{aligned} b^T ab^T a &= b^T ba^T a \\ (b^T a)^2 &= b^T ab^T a = \|b\|^2 \|a\|^2 \\ \frac{a^T b}{\|b\| \|a\|} &= 1 \end{aligned}$$

Hence the angle between the vectors needs to be 0.

## Solution to Question 9

$A$  and  $B$  are  $m \times n$ .

(a)  $A^T B$  is  $n \times n$  with  $i, j$  element

$$\sum_{k=1}^m A_{ik}^T B_{kj} = \sum_{k=1}^m A_{ki} B_{kj}$$

The trace is the sum over all  $i, i$  elements (for  $i = 1, \dots, n$ )

$$\text{tr}(A^T B) = \sum_{i=1}^n \sum_{k=1}^m A_{ki} B_{ki}$$

which we can also write with index  $j$  instead of  $k$  if we like and change the summation order and role of variables to arrive at the desired expression.

Here is an example in Julia (even though it was not required).

```
In [87]: 1 Random.seed!(0)
          2 n = 2;m=3;
          3 A = rand([1,2],n,m)
          4 B = rand([1,2],n,m)
          5 A,B
```

```
Out[87]: ([1 2 1; 1 2 1], [1 2 2; 2 1 2])
```

```
In [92]: 1 A'*B #we see the trace is 3+6+4
```

```
Out[92]: 3×3 Array{Int64,2}:
          3  3  4
          6  6  8
          3  3  4
```

```
In [93]: 1 tr(A'*B)
```

```
Out[93]: 13
```

Using the formula....

```
In [96]: 1 sum(A.*B) #element wise multiplication
```

```
Out[96]: 13
```

(b) We already showed:

$$\text{tr}(A^T B) = \sum_{i=1}^m \sum_{j=1}^n A_{ij} B_{ij}$$

The same formula with  $A$  and  $B$  switched gives:

$$\text{tr}(B^T A) = \sum_{i=1}^m \sum_{j=1}^n B_{ij} A_{ij}$$

We thus see  $\text{tr}(A^T B) = \text{tr}(B^T A)$ .

(c) From (a):  $\text{tr}(A^T A) = \sum_{i=1}^m \sum_{j=1}^n A_{ij} A_{ij}$

$$= \sum_{i=1}^m \sum_{j=1}^n A_{ij}^2 = \|A\|^2.$$

(Frobenius norm)

(d) We have

$$\text{tr}(A^T B) = \sum_{i=1}^m \sum_{j=1}^n A_{ij} B_{ij}$$

Using the same formula, and  $A^T = (A^T)^T$ ,  $B = (B^T)^T$ :

$$\text{tr}(BA^T) = \sum_{i=1}^m \sum_{j=1}^n B_{ij}^T A_{ij}^T = \sum_{i=1}^m \sum_{j=1}^n B_{ji} A_{ji}$$

and after changing indexes  $i$  and  $j$  this equals  $\text{tr}(A^T B)$ .

As an example, consider the case of  $A$  and  $B$  being vectors ( $m = n$  and  $n = 1$ ). The trace of the inner product is just the trace of a scalar. The trace of the outer product is the inner product.

## Solution to Question 10

It turns out that  $A_i = Q_i R_i$  is the QR factorization of the first  $A_i$  because every additional column in  $A$  only gives an additional column in  $Q_i$  and expands the dimension of the square matrix  $R_i$  by 1 without touching the submatrix. The two equations that show this are:

(page 97 of [VMLS] in Gram-Schmidt algorithm):

$$\tilde{q}_i = a_i - (q_1^T a_i)q_1 - \dots - (q_{i-1}^T a_i)q_{i-1}$$

(distilled page 190 in [VMLS]):

$$R_{ij} = \begin{cases} q_i^T a_j & i < j \\ \|\tilde{q}_i\| & i = j \\ 0 & i > j \end{cases}$$

**Here is a demonstration**

```
In [77]: 1 Random.seed!(0)
          2 n = 5; k = 4;
          3 A = rand([-1, 0, 1], n, k)
```

```
Out[77]: 5×4 Array{Int64, 2}:
          -1  1  1  0
           1 -1  0  1
           0 -1  1  1
           0  0 -1  1
          -1  1  0  0
```

```
In [79]: 1 rank(A) #to make sure it is full rank (rank = 4)
```

```
Out[79]: 4
```

```
In [80]: 1 F = qr(A)
```

```
Out[80]: LinearAlgebra.QRCompactWY{Float64,Array{Float64,2}}
Q factor:
5×5 LinearAlgebra.QRCompactWYQ{Float64,Array{Float64,2}}:
-0.57735  0.0  -0.516398  -0.507093  -0.377964
 0.57735  0.0  -0.258199  -0.676123   0.377964
 0.0      1.0   0.0         0.0         0.0
 0.0      0.0   0.774597  -0.507093  -0.377964
-0.57735  0.0   0.258199  -0.169031   0.755929
R factor:
4×4 Array{Float64,2}:
1.73205  -1.73205  -0.57735   0.57735
0.0      -1.0     1.0        1.0
0.0      0.0    -1.29099   0.516398
0.0      0.0     0.0       -1.18322
```

This loop shows that all sub-QR factorizations hold... notice the norms of differences are almost 0

```
In [83]: 1 for i in 1:k
2         subA = A[:,1:i]
3         subQ = F.Q[:,1:i]
4         subR = F.R[1:i,1:i]
5         println( norm(subA - subQ*subR))
6     end
```

```
1.9229626863835638e-16
2.7194799110210365e-16
2.984744261173718e-16
3.2126737200132e-16
```